



3-FINGER ADAPTIVE ROBOT GRIPPER



EASY TO USE

- Plug + Play
- UR+ certified product
- Free programming software

MAXIMUM VERSATILITY

- 4 different grip modes
- Independent finger control
- Picks objects of any size & shape

PROVEN DESIGN

- Rugged and reliable
- Fully metallic
- High payload



Pick and Place



Assembly



Quality Testing



Machine Tending

START PRODUCTION FASTER



TAKE FULL CONTROL

ADJUST THE GRIPPER'S POSITION, SPEED, AND FORCE UNTIL IT GRASPS YOUR OBJECT PERFECTLY



EXTREMELY WIDE STROKE

OPEN UP TO 155 MM WITH THE ENCOMPASSING GRIP MODE

SPECIFICATIONS

Stroke (programmable)	155 mm
Grip force (programmable)	30 to 70 N
Form-fit grip payload	10 kg
Friction grip payload	2.5 kg
Finger position repeatability (fingertip grip)	0.05 mm
Closing speed (programmable)	22 to 110 mm/s
Gripper mass	2.3 kg
Primary communication protocol	Modbus RTU (RS-485)
Secondary communication protocol options	Modbus TCP, EtherNet/IP, PROFINET, EtherCAT, DeviceNet, CANopen**