

伯朗特3008

①公司的经营宗旨:伯朗特在“完成伯朗特3008就是共同富裕”的企业文化引领下通过“重研发轻资产”的创新驱动实现共同富裕;伯朗特2022年度开始每年的净利润100%投入研发,这就是取之于民用之于民为共同富裕实现。

②伯朗特应用商规则:下单BORUNTE产品单一型号1000台给伯朗特成为一级应用商,二级应用商下单BORUNTE产品单一型号100台给一级应用商,三级100%预付 ≥ 2.85 万BORUNTE产品到二级,一、二级应用商享受20%返点,一级下单2倍返点金额伯朗特,二级下单10倍返点金额一级,一级赚10%返点,二级赚10%返点,二级100%不是消费者,因为每家一级都有1000台单一BORUNTE产品要履约,二级有100%动力把消费者报备成三级,因为已报备三级的消费者被抢就面临伯朗特永久性停止该伯朗特一级应用商接单。

③伯朗特供应链规则:付款方式:当月结现金转账。成本、品质、交期,新进入供应商必须比老供应商成本下降30%以上才能通过研发中心品质和生产中心交期的验证才能成为该产品80%的主流供应,只要您具备足够的成本、品质、交期,伯朗特的大门永远都是开放的,这就是供应链中心同事“傻瓜式”二选一谈判:“成本”不超过现有供应商且品质、交期没问题就能成为1%~20%的副供应商或者“成本”比现有供应商下降30%以上且品质、交期没问题就能成为80%以上的主供应商。

共同富裕

天人合一

我将无我

《伯朗特3008共同富裕》

BORUNTE 3008 Prosperity for all

我们的梦想
从伯朗特起航
不管再大的风浪
携起手来勇敢去闯

我们的梦想
在伯朗特发光
万亿目标的战略
要成为共同富裕的领头羊

我们的梦想
和伯朗特一起飞翔
共同富裕的实现
有您有我有爱的力量

1 = D 原唱: 尹贵超 词曲: 尹荣造
0 0 0 3 4 | 5 - 0 1 7 | 1 5. 0 3 5 | 1 i. 0 1 2 |
伯朗 特 3 0 0 8 共同 富裕, 凝成
7. 6 6 5. 3 5 | 6 5. 0 3 2 | 2 1. 0 6 1 |
一 条 路, 我将 无 我, 天人 合 一, 我们
2. 1 1 3 2 6 1 | 2 0 4. 3 3 4 | 5 - 3 5 | i. i.
尽 管 努 力 伯 郎 特 自 有 安 排, 保 证 完 成,
i 2 | 3 2 i. 3 5 | i 7 i 7 6 0 3 4 | 5. 5 5 6
坚 决 完 成, 世 界 的 共 同 富 裕, 我 们 道 远 任
5 0 3 5 | i. i 0 i 2 | 3 2 i 0 3 5 | i 7 6.
重, 共 同 富 裕, 世 界 大 同, 创 新 促 永 续,
6 7 | i 7 i 2 2 0 6 i | 2 i 2 2 - | 3 2
勇 攀 巍 峰, 完 成 伯 郎 特 3 0
i 2 6 0 6 i | 2. 5 3 i | 2 - 2 0 6 i | 2 i 2
0 8 就 是 共 同 富 裕, 完 成 伯 郎
2 - 2 0 | 3 2 i 2 6 0 6 i | 2. 5 3 7 | i - - ||
特 3 0 0 8 就 是 共 同 富 裕。

共同富裕

伯朗特 3008

《1.11伯朗特文化节是共同富裕的“伯朗特宣言”》

伯朗特文化节
它是宣言书
向共同富裕发出呐喊
王侯将相宁有种乎?

伯朗特文化节
它是播种机
在共同富裕播洒希望
星星之火,可以燎原!

伯朗特文化节
它是指明灯
为共同富裕指明方向
路途遥远、行则将至!

1.11伯朗特文化节
一场共同富裕的饕餮盛宴
共同富裕,世界大同
同心者同路!

BRTIRXZ Series

协作机器人
Axis Robot

P点可达区域

HISTORICAL

BRTIRXZ0805A是伯朗特自主研发的一款带拖动示教功能的六轴协作机器人，其最大负载为5KG,最大臂展可达870mm。具有碰撞检测、轨迹复现等功能。同时具有安全高效、智能易用、灵活轻巧、经济可靠和低功耗等特点，大大满足客户对人机协作方面的需求。其高灵敏性和快响应性可适用于高密集的柔性化生产线，满足产品包装、注塑、上下料、装配等作业需要，尤其对人机协同作业的应用需求，更是出类拔萃。

防护等级高—IP54，防尘，防水。

精度高—重复定位精度±0.03mm。

BRTIRXZ0805A is a six-axis cooperative

drag-teaching function independently developed by BORUNTE, with a maximum load of 5KG and a maximum arm length of 870mm. It has the functions of collision detection and track reproduction. At the same time, it is safe and efficient, intelligent and easy to use, flexible and light, economical and reliable, low power consumption and other characteristics, which greatly meet the needs of customers in man-machine cooperation. Its high sensitivity and quick response can be applied to high density flexible production line, to meet the needs of product packaging, injection molding, loading and unloading, assembly and other operations, especially for man-machine collaborative work application demand, is outstanding.

The protection grade reaches IP54.
Dust proof and water proof.

Dust-proof and water-proof.
The repeat positioning accu-

The repeat positioning accuracy is $\pm 0.03\text{mm}$.

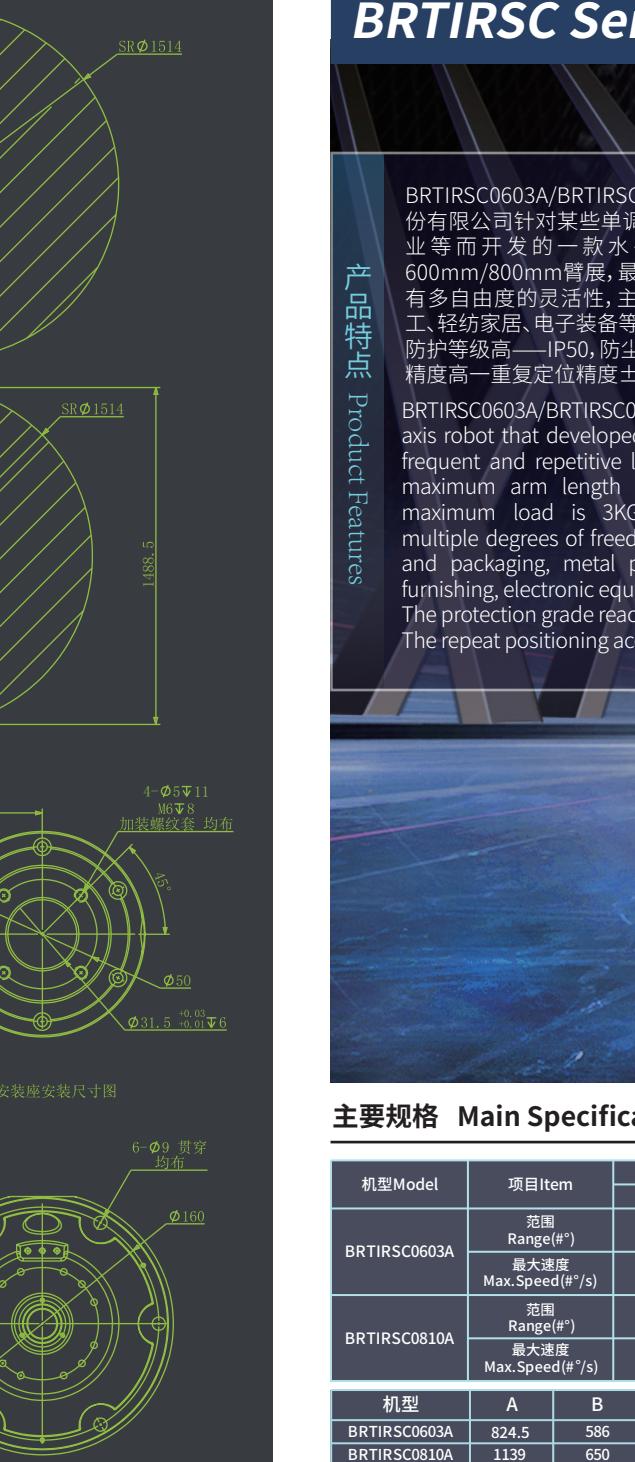
主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRXZ0805A	臂展 Arm Length(mm)	地面-2轴距 138mm		2-3轴距 390mm	3-4轴距 367mm		5轴-端面距 91mm	870	5	±0.03	5.5	约26
	范围 Range(°)	±180°	±160°	-65°/+250°	±180°	±180°	±360°					
	最大速度 Max.Speed(°/s)	120°/s	120°/s	120°/s	180°/s	180°/s	180°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

Without further notice if specification and exterior have been changed because of improvement. Thanks for your understanding.

机器



四轴机器人
Four-axis Robot

2

8500

Y

5700

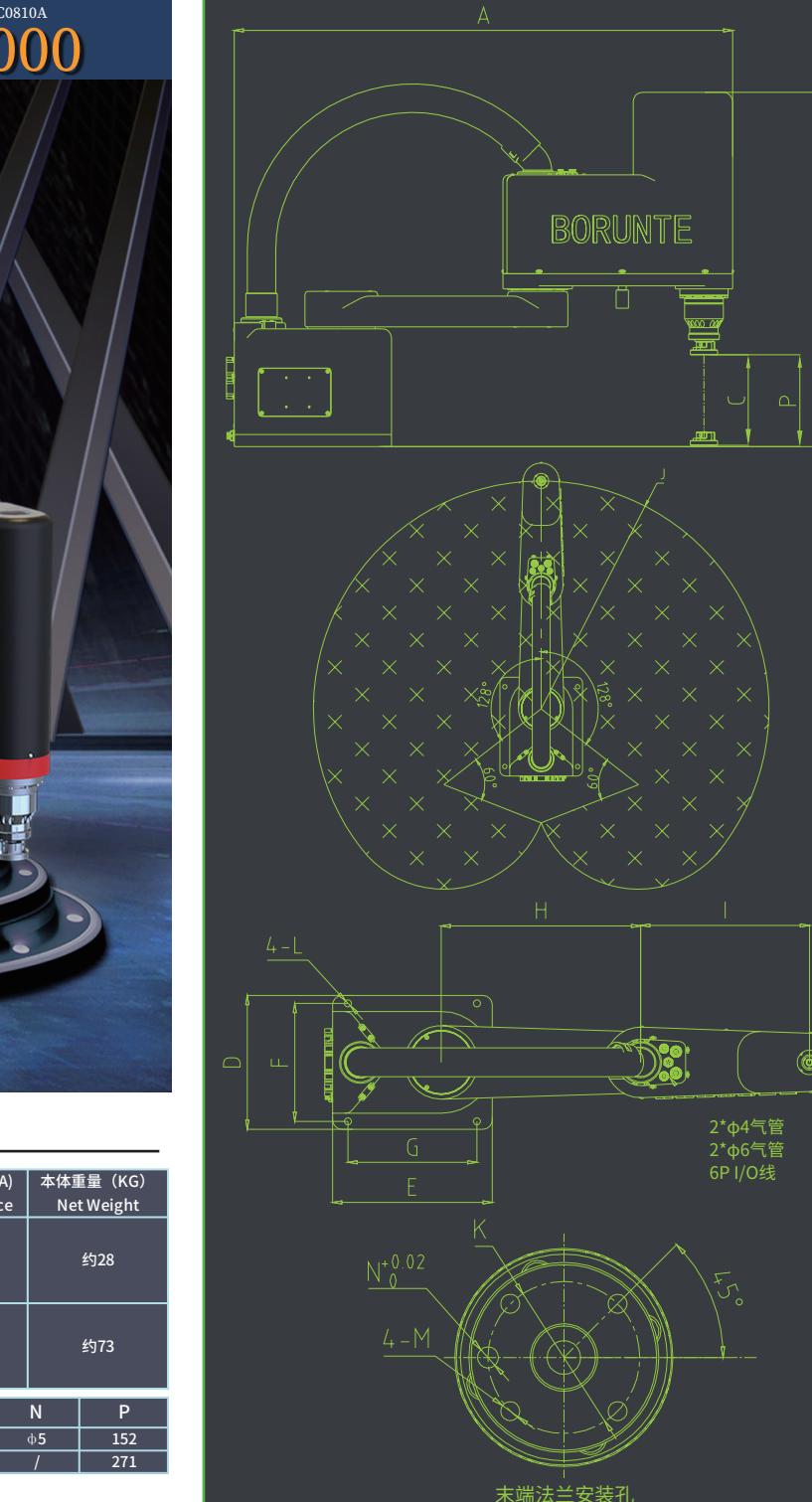
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变更时，不再另行通知，敬请谅解。

ation and exterior have been changed because of improvement. Thanks for your

44



BRTIRPL Series

四轴机器人
Four-axis Robot

¥ 57000



主要规格 Main Specification

产品型号 Model	项目 Item	主动臂 Master Arm		末端 End	臂长 Arm Length	负载 Loading ability	位置重复定位精度 Accuracy of position	角度重复定位精度 Angle repeat positioning	允许负载最大转动惯量 Maximum allowable moment of inertia of load	电源电容 Power Source	本体重量 Net Weight							
		上摆 Upper	下摆 Hem															
BRTIRPL1003A	臂长 (mm) Arm Length	安装面-行程区域距872.5mm		1000mm	3KG	±0.1mm	±0.5°	0.01KG/m²	3.3KVA	约103								
	范围 Range (#) Max.Speed (#/s)	46.7°	86.6°															
	节拍 (次/min) Cycle Time (min⁻¹)	行程: 25/305/25 (mm)									150次/min							
		150次/min																

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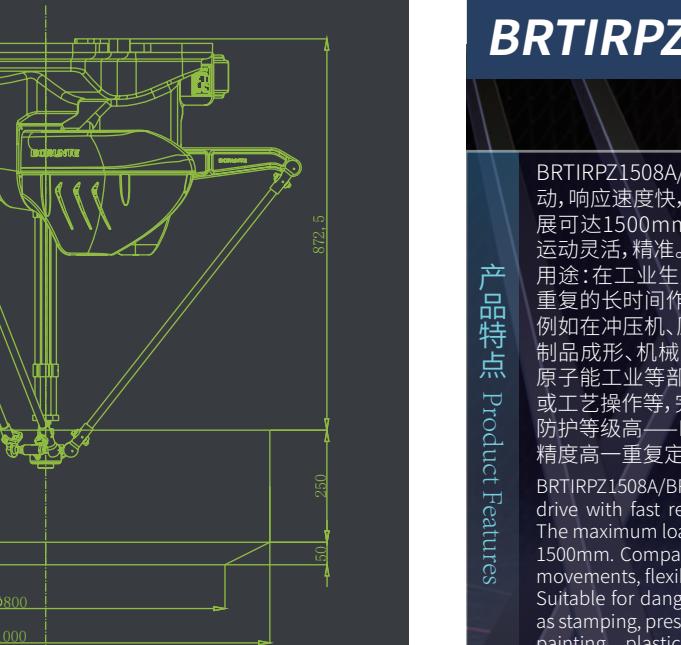
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BRTIRPZ Series

四/五轴机器人
Four-axis Robot

¥ 57000

¥ 120000

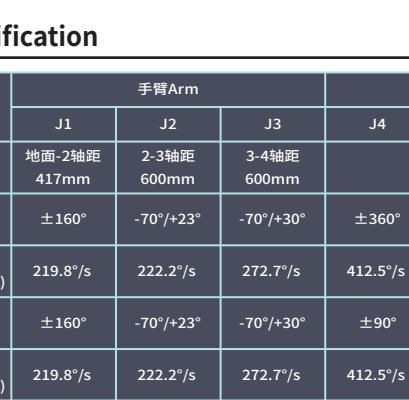


BRTIRPZ Series

四/五轴机器人
Four-axis Robot

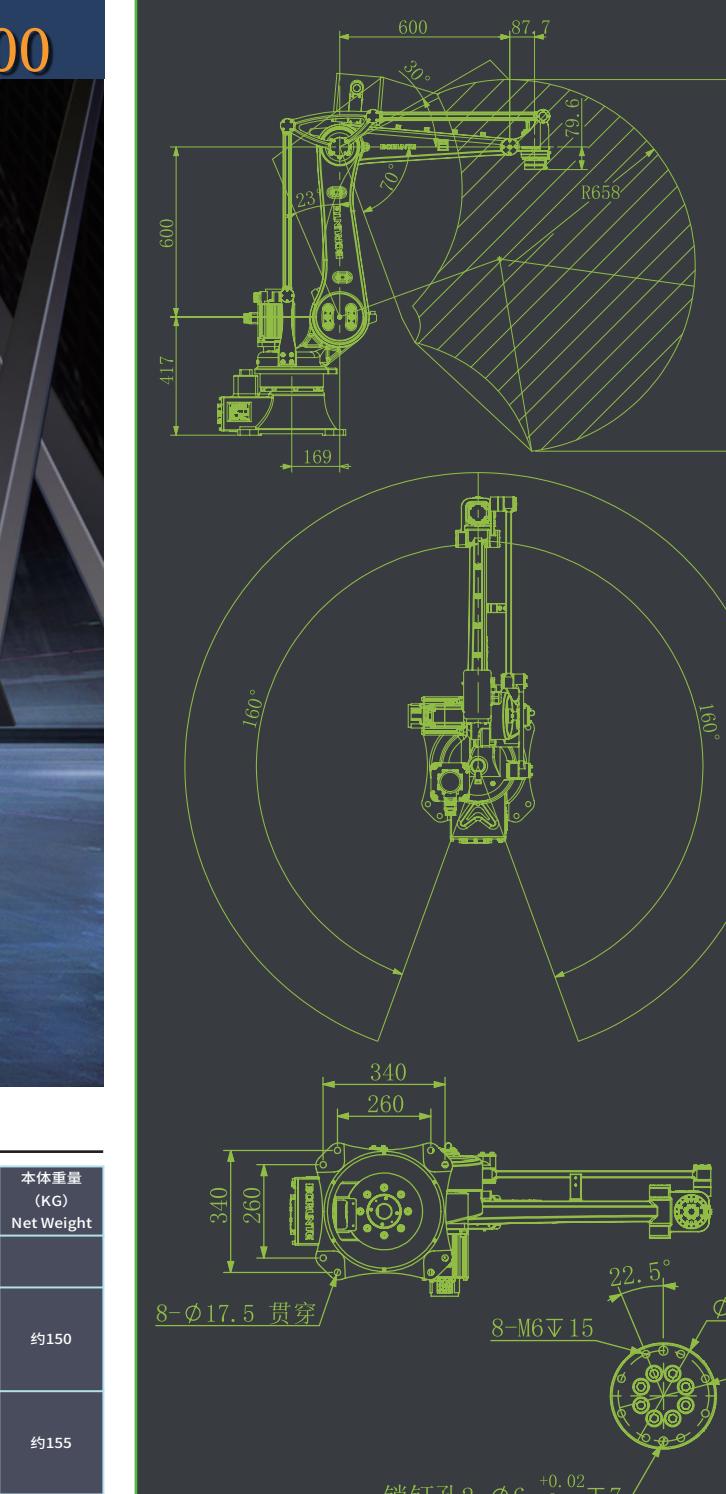
¥ 57000

¥ 120000



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BRTIRPZ Series

四轴机器人
Four-axis Robot

¥ 120000

产品特点 Product Features

BRTIRPZ1825A是伯朗特机器人股份有限公司针对某些单调、频繁和重复的长时间作业,或是危险、恶劣环境下的作业等而开发的一款四轴码垛机器人,其拥有1800mm臂展,最大负载可达25kg,具有多自由度的灵活性,对上下料、搬运、拆垛、码垛等场景能够应对自如。

防护等级高-IP50 防尘。

精度高—重复定位精度±0.08mm。

BRTIRPZ1825A type robot is a four-axis stacking robot that developed for some monotonous,frequent and repetitive long-term operations or operations in dangerous and harsh environments. The maximum arm length is 1800mm. The maximum load is 25KG,it's flexible with multiple degrees of freedom. Suitable for loading and unloading, handling, dismantling and stacking etc. The protection grade reaches IP50. Dust-proof. The repeat positioning accuracy is ±0.08mm.

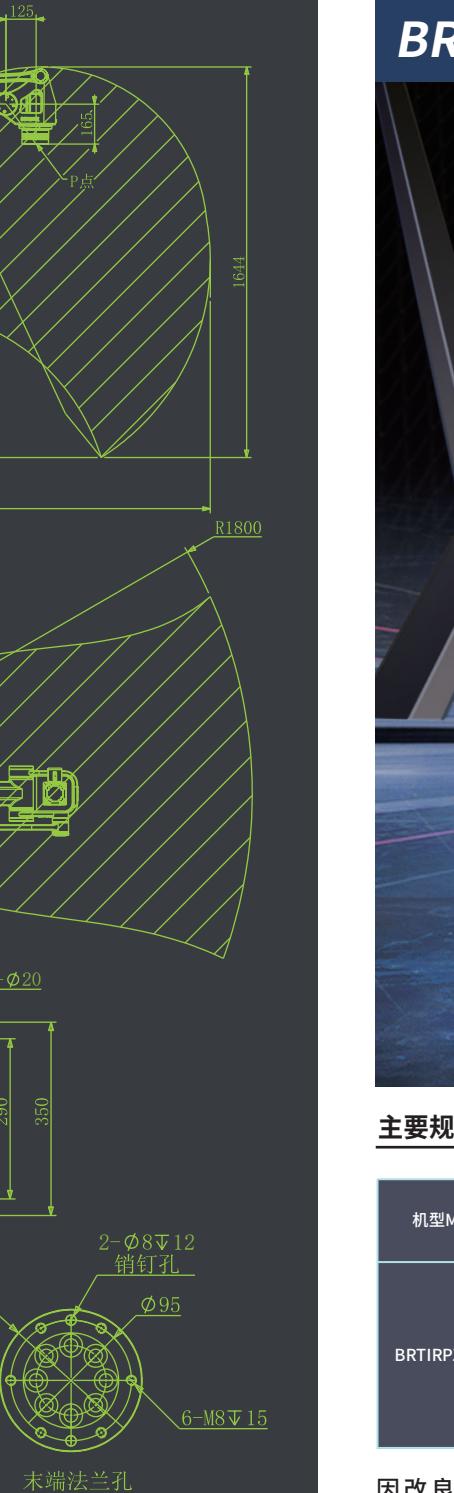


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm		手腕 Wrist		臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4					
BRTIRPZ1825A	臂展 Arm Length(mm)	地面-2轴距 502.6mm		2-3轴距 760mm		1800	25	±0.08	6	约256
	范围 Range(°)	±155°	-70°/+30°	-62°/+25°	±360°					
	最大速度 Max.Speed(°/s)	175°/s	135°/s	123°/s	300°/s					

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末端法兰孔

BRTIRPZ Series

四轴机器人
Four-axis Robot

¥ 200000

产品特点 Product Features

BRTIRPZ2250A是伯朗特机器人股份有限公司针对某些单调、频繁和重复的长时间作业,或是危险、恶劣环境下的作业等而开发的一款四轴码垛机器人,其拥有2200mm臂展,最大负载可达50kg,具有多自由度的灵活性,对上下料、搬运、拆垛、码垛等场景能够应对自如。

防护等级高-IP50,防尘。

精度高—重复定位精度±0.1mm。

BRTIRPZ2250A type robot is a stacking robot that developed for some monotonous, frequent and repetitive long-term operations or operations in dangerous and harsh environments. The maximum arm length is 2200mm. The maximum load is 50KG. It's flexible with multiple degrees of freedom.Suitable for loading and unloading,handling, dismantling and stacking etc. The protection grade reaches IP50. Dust-proof. The repeat positioning accuracy is ±0.1mm.

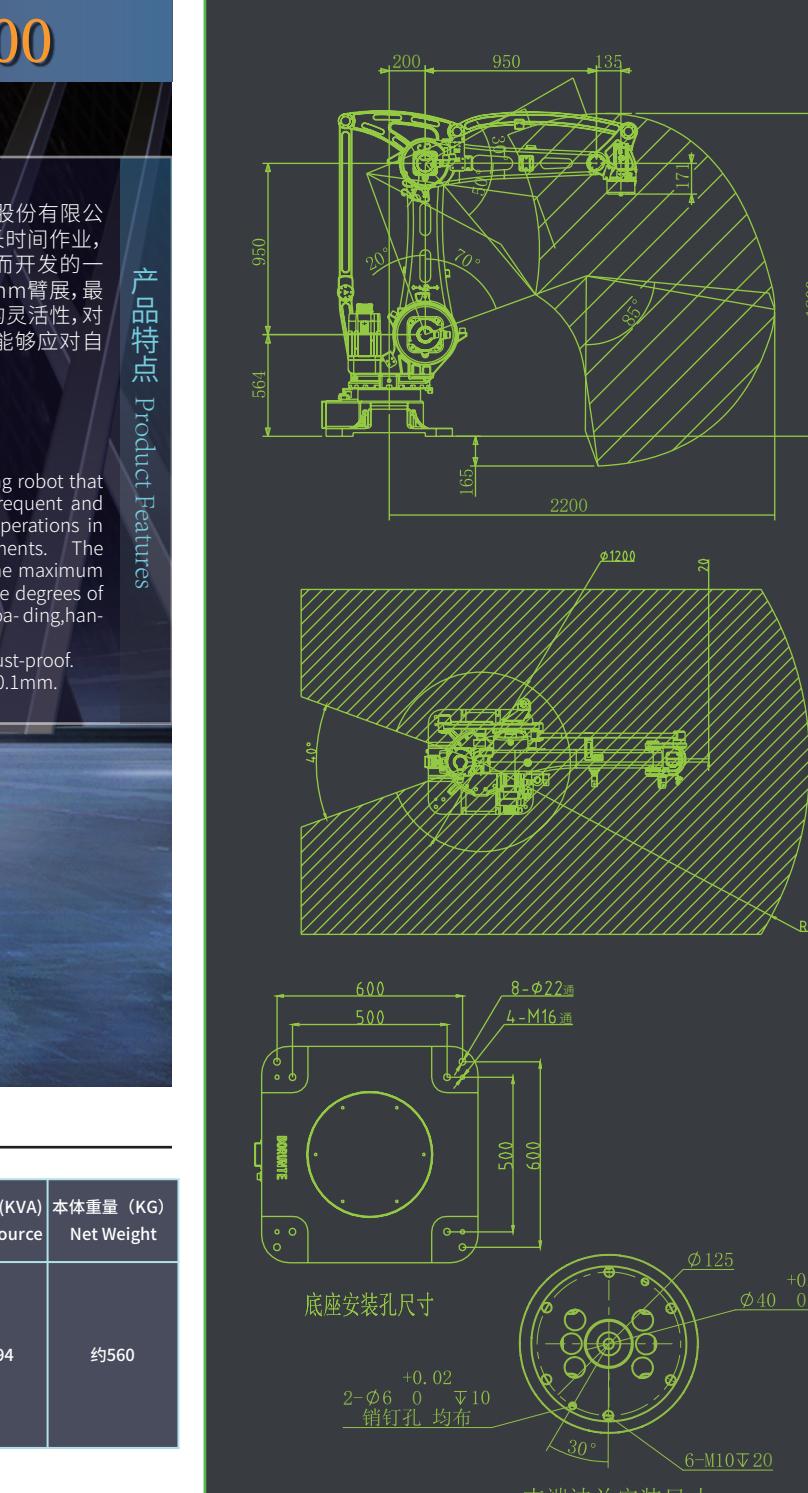


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm		手腕 Wrist		臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4					
BRTIRPZ2250A	臂展 Arm Length(mm)	地面-2轴距 564mm	2-3轴距 950mm	3-4轴距 950mm	4轴-端面距 135mm	2200	50	±0.1	12.94	约560
	范围 Range(°)	±160°	-70°/+20°	-50°/+30°	±360°					
	最大速度 Max.Speed(°/s)	84°/s	70°/s	108°/s	198°/s					

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末端法兰安装尺寸

BRTIRPZ Series

四轴机器人
Four-axis Robot

¥ 285000

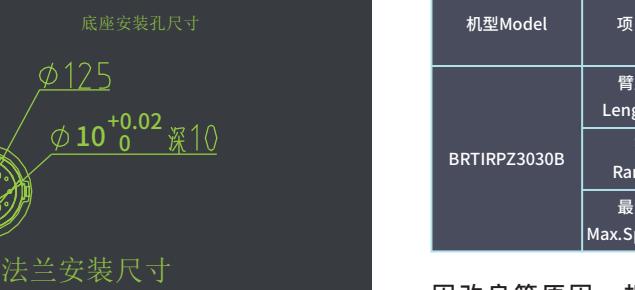
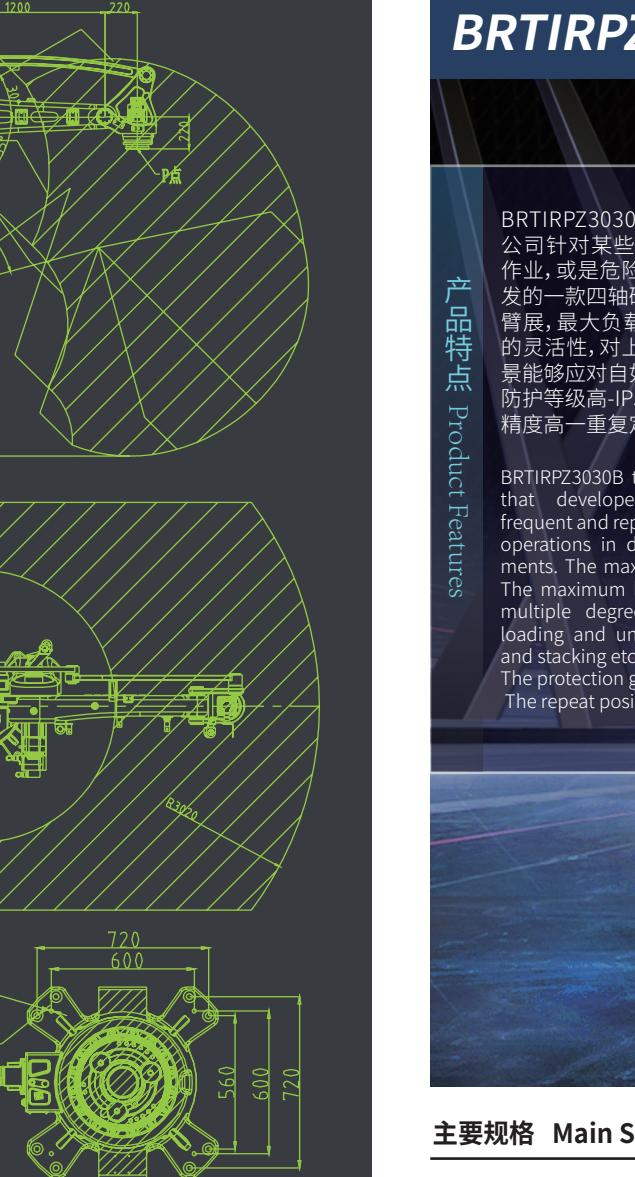


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm		手腕 Wrist		臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4					
BRTIRPZ3013A	臂展Arm Length(mm)	地面-2轴距 616.5mm	2-3轴距 1200mm	3-4轴距 1200mm		3020	130	±0.15	23	约1200
	范围 Range(°)	±160°	-75°/+30°	-55°/+30°	±180°					
	最大速度 Max.Speed(°/s)	57°/s	53°/s	53°/s	150°/s					

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BRTIRPZ Series

四轴机器人
Four-axis Robot

¥ 570000

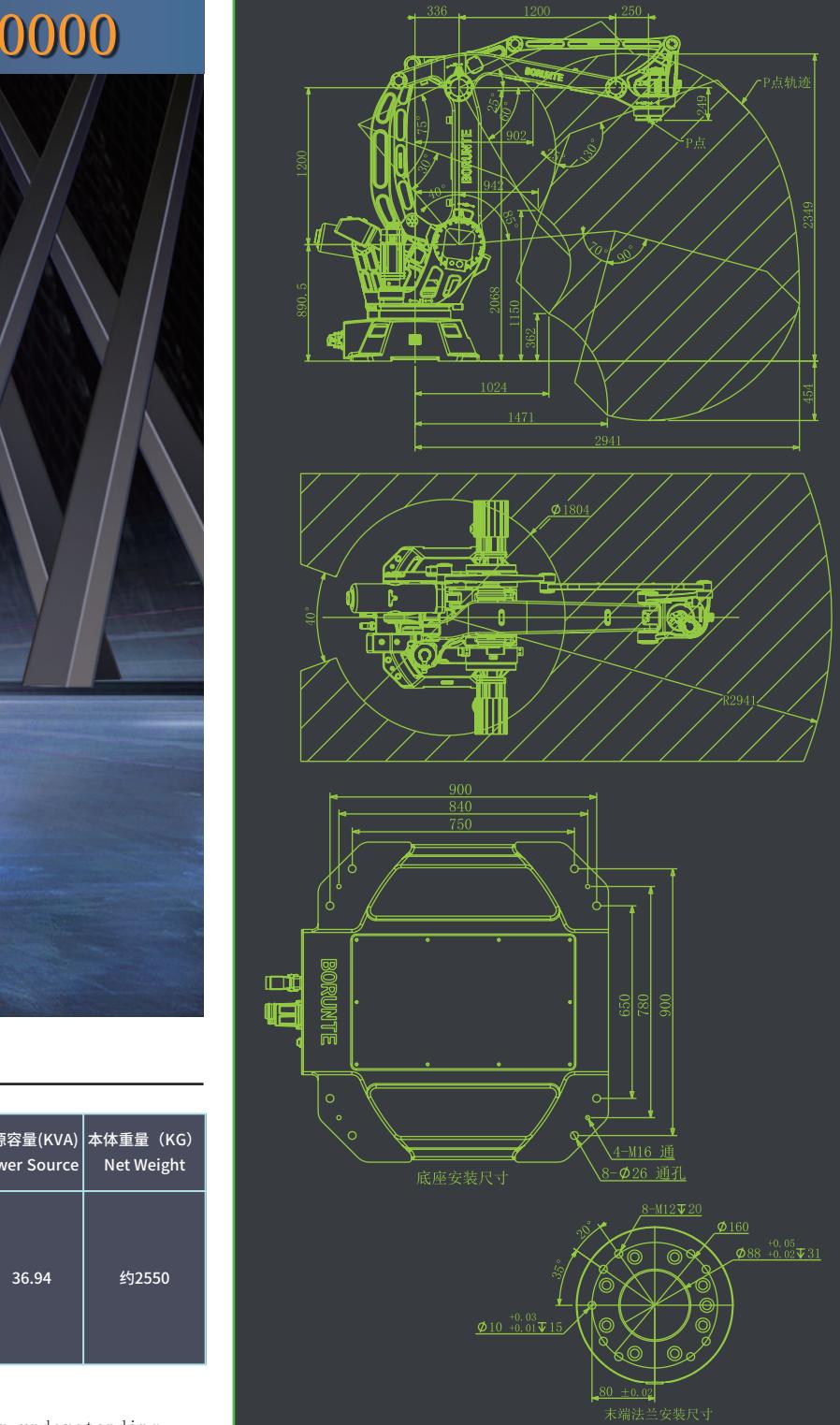


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm		手腕 Wrist		臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4					
BRTIRPZ3030B	臂展Arm Length(mm)	地面-2轴距 890.5mm	2-3轴距 1200mm	3-4轴距 1200mm	4轴-端面距 250mm	2950	300	±0.2	36.94	约2550
	范围 Range(°)	±160°	-85°/+40°	-60°/+25°	±360°					
	最大速度 Max.Speed(°/s)	53°/s	63°/s	63°/s	150°/s					

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机器人系列 Industrial Robot

机器人系列 Industrial Robot

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 120000

产品特点 Product Features

BRTIRUS0401A是伯朗特机器人股份有限公司针对微小型零部件作业环境设计的，适用于小型零部件组装、分拣、检测等作业，额定负载1KG，臂展465mm，在同等级负载的六轴机器人中具有最高水平运行速度和较广泛的运行范围，具有高精度、高速度和高灵活性的特点。
防护等级高—IP54，防尘防水。
精度高—重复定位精度±0.02mm。

BRTIRUS0401A is designed by Braun Robot Co., Ltd. for the operation environment of micro and small parts. It is suitable for small parts assembly, sorting, detection and other operations. The rated load is 1KG, the arm span is 465mm, and it has the highest level of operation speed and a wide range of operation among six-axis robots with the same load. It features high precision, high speed and high flexibility.
The protection grade reaches IP54.
Dust-proof and water-proof.
The repeat positioning accuracy is ±0.02mm.

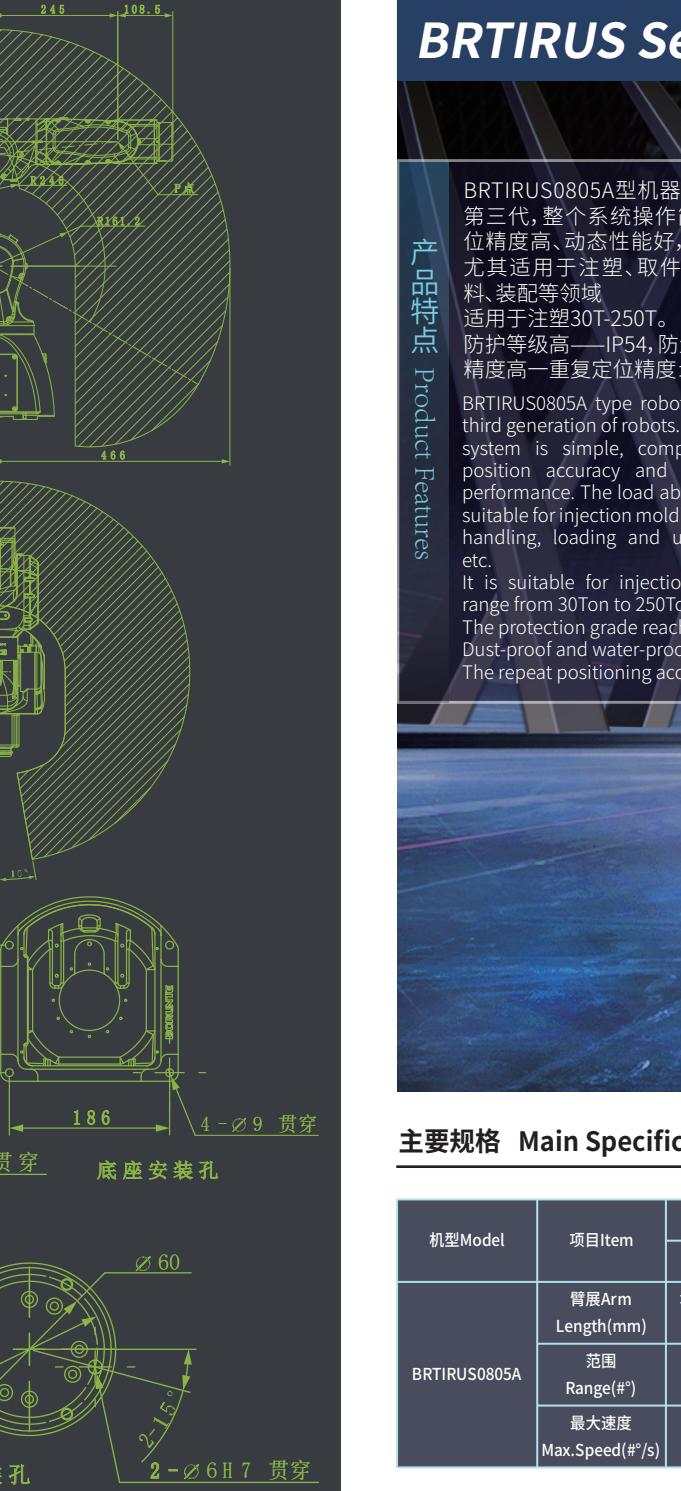


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量 (KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS0401A	臂展Arm Length(mm)	地面-2轴距 302mm		2-3轴距 220mm		3-5轴距 245mm	5轴-端面距 108.5mm	465	1	±0.02	1	约20
	范围 Range(°)	±160°	-60°/+120°	-210°/+50°	±180°	±120°	±360°					
	最大速度 Max.Speed(°/s)	375°/s	297°/s	375°/s	562.5°/s	600°/s	600°/s					

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机器人系列 Industrial Robot

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 57000

产品特点 Product Features

BRTIRUS0805A型机器人是伯朗特机器人第三代，整个系统操作简单、结构紧凑、定位精度高、动态性能好，其5kg的负载能力尤其适用于注塑、取件、冲压、搬运、上下料、装配等领域。
适用于注塑30T-250T。
防护等级高—IP54，防尘防水。
精度高—重复定位精度±0.05mm。

BRTIRUS0805A type robot is BORUNTE's the third generation of robots. The whole operation system is simple, compact structure, high position accuracy and has good dynamic performance. The load ability is 5kg, especially suitable for injection molding,taking, stamping, handling, loading and unloading, assembly, etc.
It is suitable for injection molding machine range from 30Ton to 250Ton.
The protection grade reaches IP54.
Dust-proof and water-proof.
The repeat positioning accuracy is ±0.05mm.

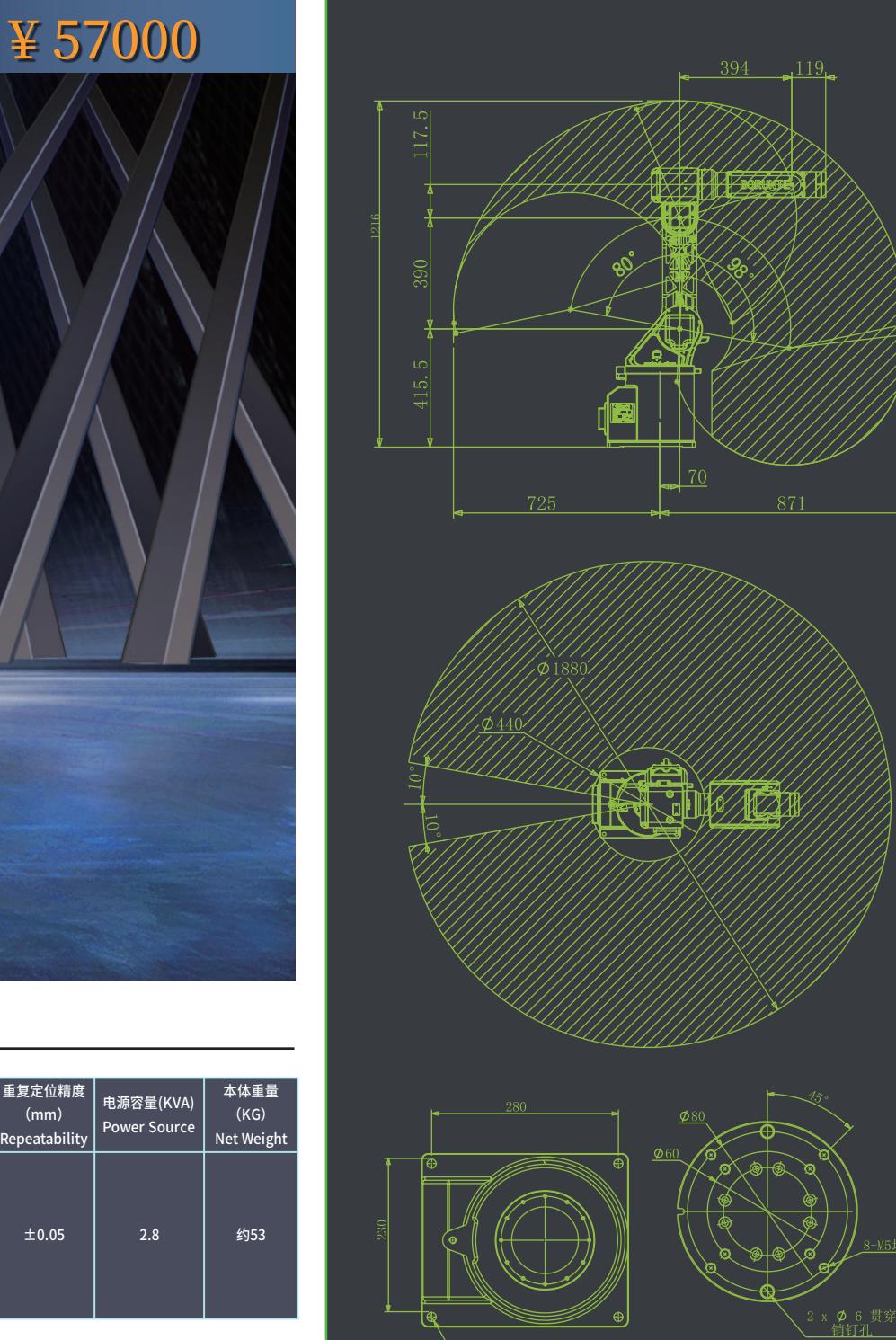


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS0805A	臂展Arm Length(mm)	地面-2轴距 415.5mm		2-3轴距 390mm		3-5轴距 394mm	5轴-端面距 119mm	940	5	±0.05	2.8	约53
	范围 Range(°)	±170°	-98°/+80°	-80°/+95°	±180°	±120°	±360°					
	最大速度 Max.Speed(°/s)	237°/s	267°/s	370°/s	337°/s	600°/s	588°/s					

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机器人系列 Industrial Robot

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 120000



产品特点 Product Features

BRTIRUS0707A是伯朗特机器人股份有限公司针对某些单调、频繁和重复的长时间作业，或是危险、恶劣环境下的作业等而开发的一款六轴工业机器人，其拥有700mm臂展，最大负载可达7kg。具有多自由度的灵活性，对打磨、装配、喷涂等场景能够应对自如。

防护等级高—IP54,防尘防水。

精度高—重复定位精度±0.03mm。

BRTIRUS0707A type robot is a six axis robot that developed for some monotonous, frequent and repetitive long-term operations or operations in dangerous and harsh environments. The maximum arm length is 700mm. The maximum load is 7KG. It's flexible with multiple degrees of freedom. Suitable for polishing, assembling, painting, etc. The protection grade reaches IP54. Dust-proof and water-proof.

The repeat positioning accuracy is ±0.03mm.

主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS0707A	臂展Arm Length(mm)	地面-2轴距 449.5mm		2-3轴距 350mm		3-5轴距 357.5mm		5轴-端面距 164.5mm				
	范围 Range(#°)	±168°	±100°	-60°/+140°	±180°	±115°		±360°				
	最大速度 Max.Speed(#°/s)	266°/s	300°/s	375°/s	330°/s	300°/s		375°/s				

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

Without further notice if specification and exterior have been changed because of improvement. Thanks for your understanding.



顶部安装尺寸
2-M5V10
末端法兰安装尺寸

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 120000



产品特点 Product Features

BRTIRUS1510A是伯朗特机器人股份有限公司针对多自由度的复杂应用而开发的六轴机器人，其最大负载可达10kg,拥有1500mm臂展。采用轻量式手臂设计，机械结构紧凑、简洁，在高速运动状态下，能够在狭小工作空间内进行灵活作业，满足柔性化生产需要。具有六个自由度的灵活性，对上下料、注塑、压铸、装配、涂胶、打磨、检测等场景能够随心所欲。

操作简单—采用华成控制系统。

适用于注塑机:200T-600T。

防护等级高—IP50,防尘。

精度高—重复定位精度±0.05mm。

BRTIRUS1510A is a six-axis robot developed by BORUNTE ROBOT Co.,Ltd. for complex applications with multiple degrees of freedom.The maximum load is 10KG, the maximum arm length is 1500mm. Lightweight arm design, compact mechanical structure, simple, in the state of high speed movement, can be carried out in a small workspace flexible work, meet the needs of flexible production. It has six degrees of flexibility.Suitable for painting, welding, molding, stamping, forging, handling, loading, assembling, etc.

It adopts HC control system. It is suitable for injection molding machine range from 200Ton to 600Ton.

The protection grade reaches IP50.Dust-proof.

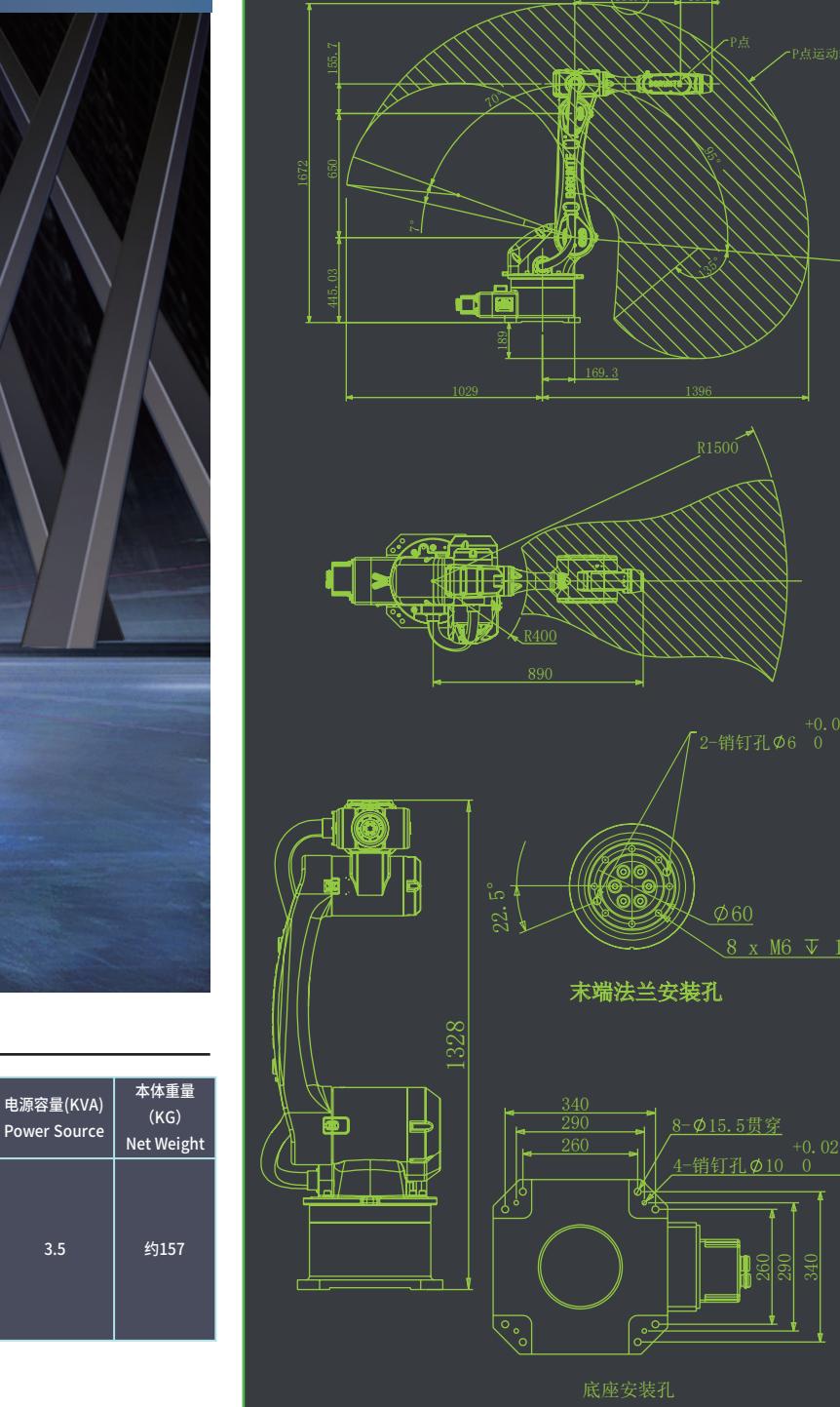
The repeat positioning accuracy is ±0.05mm.

主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS1510A	臂展Arm Length(mm)	地面-2轴距 445.03mm		2-3轴距 650mm		3-5轴距 555.9mm		5轴-端面距 165mm				
	范围 Range(#°)	±165°	-95°/+70°	-85°/+95°	±180°	±115°	±360°					
	最大速度 Max.Speed(#°/s)	148°/s	148°/s	223°/s	250°/s	270°/s	337°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

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机器人系列 Industrial Robot

BRTIRWD Series 六轴机器人

Six-axis Robot

¥ 120000

产品特点 Product Features

BRTIRWD1506A是伯朗特机器人股份有限公司针对焊接应用行业开发的六轴机器人。机器人结构紧凑、体积小、重量轻、最大负载6KG,臂展1600mm,腕部采用中空结构,走线更方便、动作更灵活。
防护等级高—手腕 IP54,本体 IP50,防尘防水。
精度高—重复定位精度±0.05mm。

BRTIRWD1506A six axis industrial robot is BORUNTE ROBOT Co.,Ltd. designed for the development of the welding application industry. The robot has compact structure, small volume and light weight. Its maximum load is 6KG and its arm span is 1600mm. Wrist hollow structure, more convenient line, more flexible action. One, two and three joints are installed with high-precision reducer, four and six joints are equipped with high-precision gear structure, high-speed joint speed can be flexible operation. The protection grade reaches IP54 at the end and IP50 at the body. Dust-proof and water-proof. The repeat positioning accuracy is ±0.05mm.

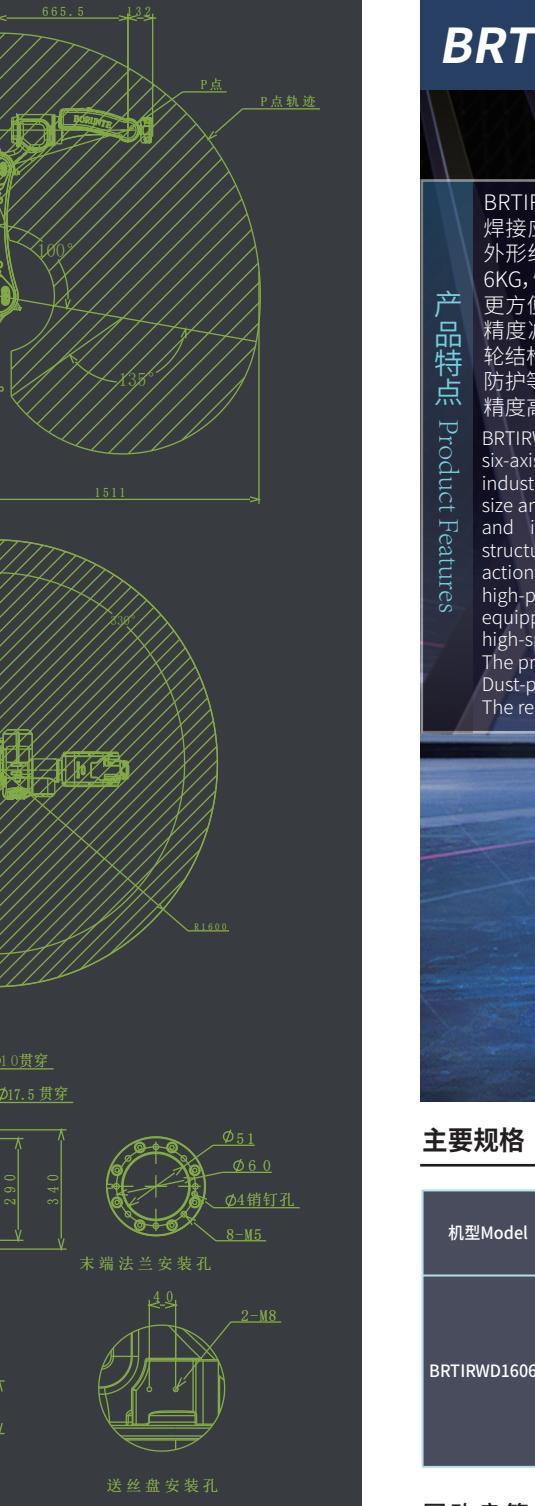


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量 (KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRWD1506A	臂展Arm Length(mm)	1-2轴水平距 170mm	地面-2轴距 488mm	2-3轴距 650mm	3-5轴垂直距 200mm	3-5轴水平距 625.5mm	5轴-法兰端面 距132mm	1600	6	±0.05	3.8	约166
	范围 Range(°)	±165°	-75°/+100°	±82°	±150°	±110°	±360°					
	最大速度 Max.Speed(°/s)	163°/s	148°/s	223°/s	168°/s	270°/s	703°/s					

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机器人系列 Industrial Robot

BRTIRWD Series 六轴机器人

Six-axis Robot

¥ 120000

产品特点 Product Features

BRTIRWD1606A六轴工业机器人是一款针对焊接应用行业开发的六轴机器人。机器人的外形结构紧凑,体积小、重量轻、其最大负载6KG,臂展1600mm,腕部采用中空结构,走线更方便、动作更灵活。一二三关节均安装了高精度减速机,四五六关节均采用了高精度齿轮结构,高速的关节速度能进行灵活的作业。
防护等级高—IP54,防尘防水。
精度高—重复定位精度±0.05mm。

BRTIRWD1606A Six-axis industrial robot is a six-axis robot developed for welding application industry. The robot is compact in shape, small in size and light in weight. Its maximum load is 6KG and its arm span is 1600mm. Wrist hollow structure, more convenient line, more flexible action. One, two and three joints are installed with high-precision reducer, four and six joints are equipped with high-precision gear structure, high-speed joint speed can be flexible operation. The protection grade reaches IP54. Dust-proof and water-proof. The repeat positioning accuracy is ±0.05mm.

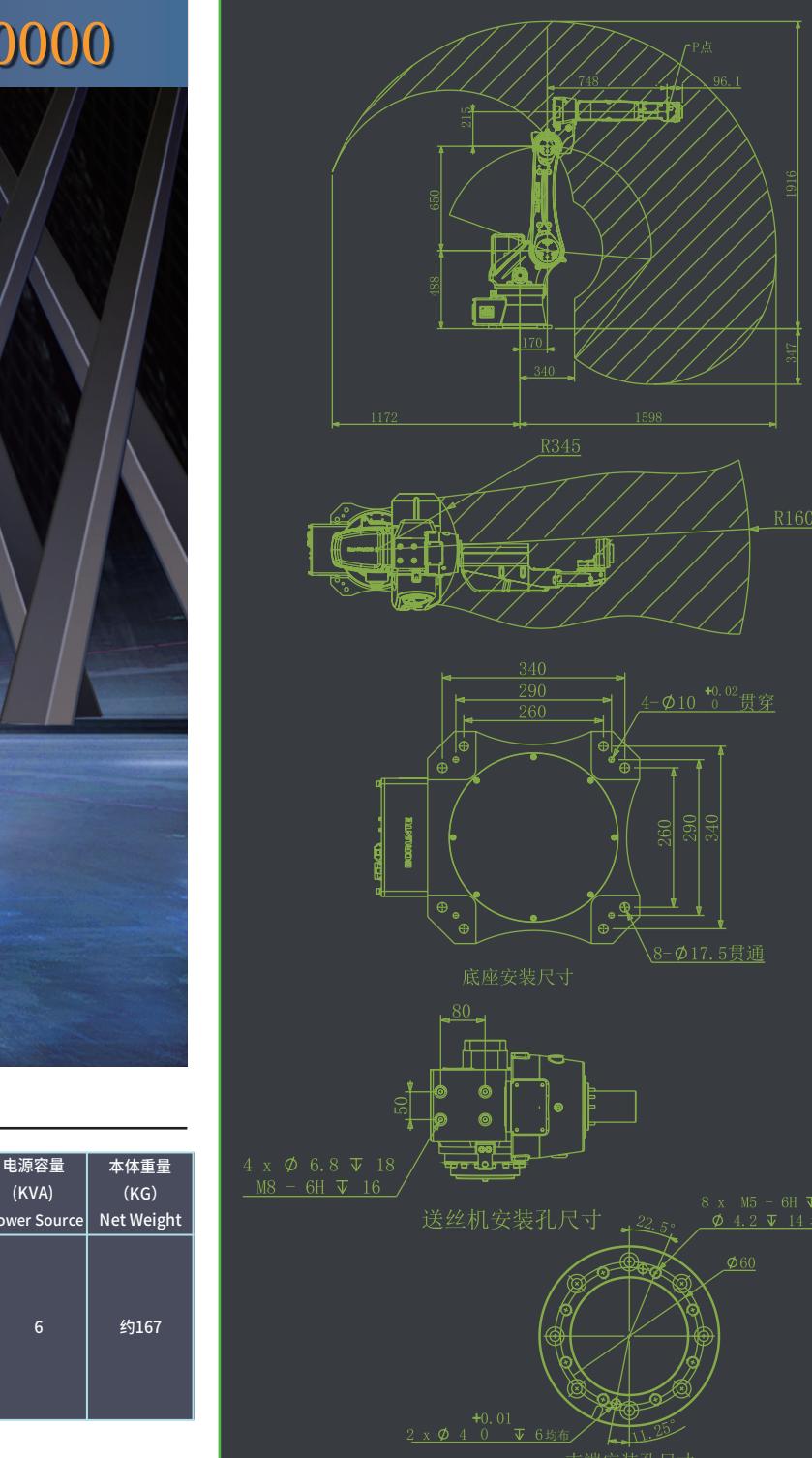


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量 (KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRWD1606A	臂展Arm Length(mm)	地面-2轴距 488mm	1-2轴距 170mm	2-3轴距 650mm	3-4轴距 215mm	3-5轴距 748mm	5轴-端面距 96.1mm	1600	6	±0.05	6	约167
	范围 Range(°)	±165°	-95°/+70°	±90°	±155°	±130°	±360°					
	最大速度 Max.Speed(°/s)	163°/s	148°/s	223°/s	250°/s	300°/s	500°/s					

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机器人系列 Industrial Robot

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 120000

产品特点 Product Features

BRTIRUS1820A是伯朗特机器人股份有限公司针对多自由度的复杂应用而开发的六轴机器人，其最大负载可达20kg,采用轻量式手臂设计，机械结构紧凑、简洁，在高速运动状态下，能够在狭小工作空间内进行灵活作业，满足柔性化生产需要。具有六个自由度的灵活性，对上下料、注塑、压铸、装配、涂胶、打磨、检测等场景能够随心所欲。适用于注塑机:500T-1300T。
防护等级高—手腕IP54、本体IP50,防尘防水。
精度高—重复定位精度±0.05mm。

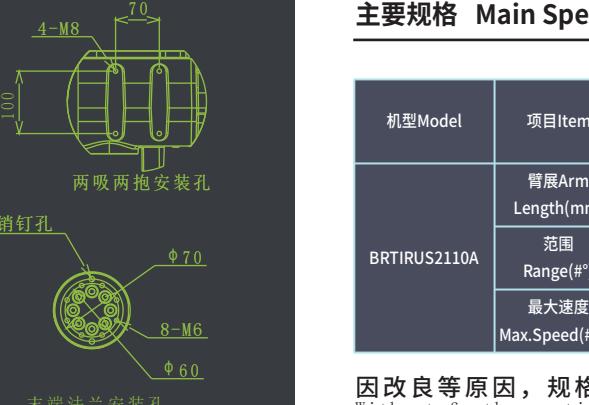
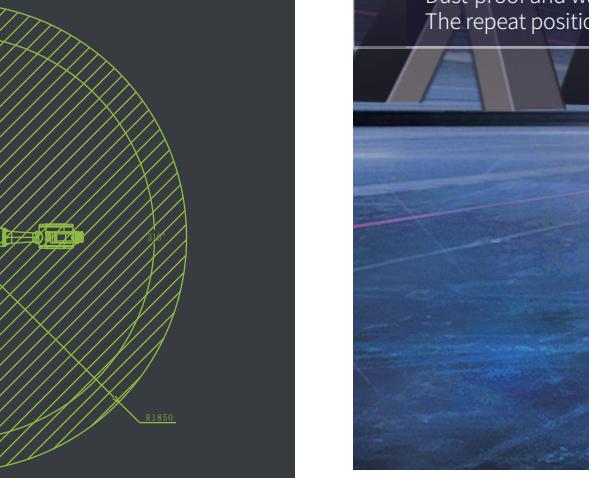
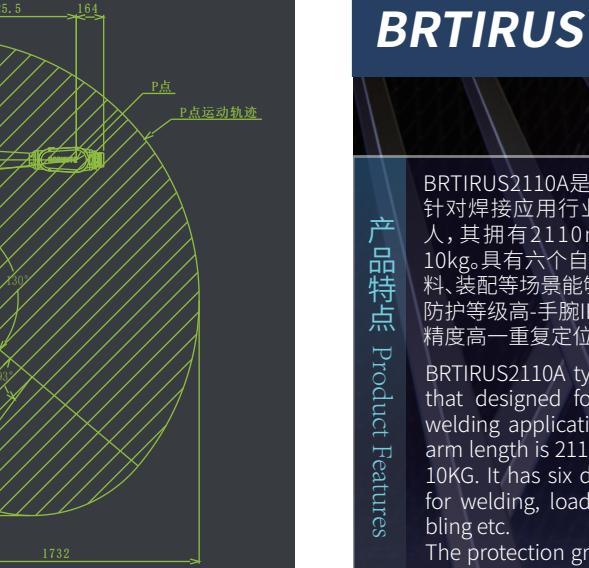
BRTIRUS1820A is a six-axis robot developed by BORUNTE ROBOT Co.,Ltd. for complex applications with multiple degrees of freedom. The maximum load is 20KG, the maximum arm length is 1850mm. Lightweight arm design, compact mechanical structure, simple, in the state of high speed movement, can be carried out in a small workspace flexible work, meet the needs of flexible production. It has six degrees of flexibility.Suitable for loading and unloading, injection machine, die casting, assembling, coating industry, polishing, detection etc. It is suitable for injection molding machine range from 500 Ton to 1300 Ton.
The protection grade reaches IP54 at the end and IP50 at the body.
Dust-proof and water-proof.
The repeat positioning accuracy is ±0.05mm.

主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS1820A	臂展Arm Length(mm)	地面-2轴距 494.6mm		2-3轴距 730mm		3-5轴距 825.5mm	5轴-端面距 117mm	1850	20	±0.05	6.2	约230
	范围 Range(°)	±155°	-130°/+75°	-75°/+135°	±180°	±115°	±360°					
	最大速度 Max.Speed(°/s)	122°/s	162°/s	136°/s	273°/s	300°/s	375°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

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BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 120000

产品特点 Product Features

BRTIRUS2110A是伯朗特机器人股份有限公司针对焊接应用行业开发的一款六轴工业机器人，其拥有2110mm长臂展,最大负载可达10kg,具有六个自由度的灵活性,对焊接、上下料、装配等场景能够应对自如。防护等级高—手腕IP54、本体IP50,防尘防水。精度高—重复定位精度±0.05mm。

BRTIRUS2110A type robot is a six axis robot that designed for the development of the welding application industry. The maximum arm length is 2110mm. The maximum load is 10KG. It has six degrees of flexibility.Suitable for welding, loading and unloading, assembling etc.

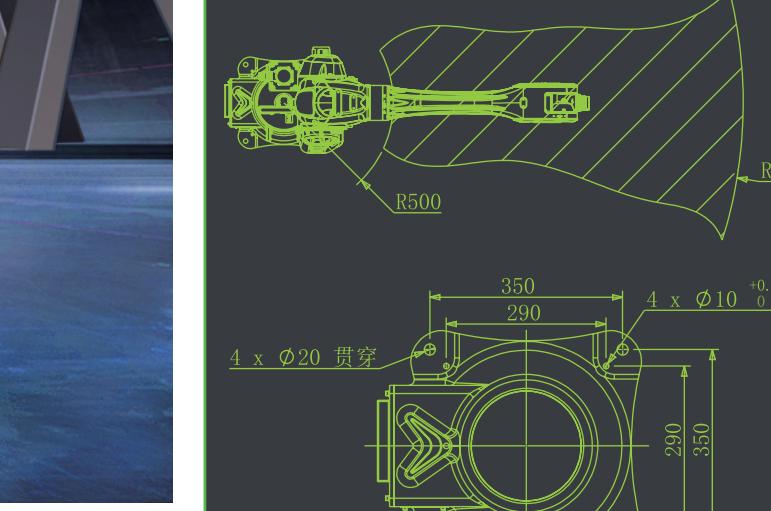
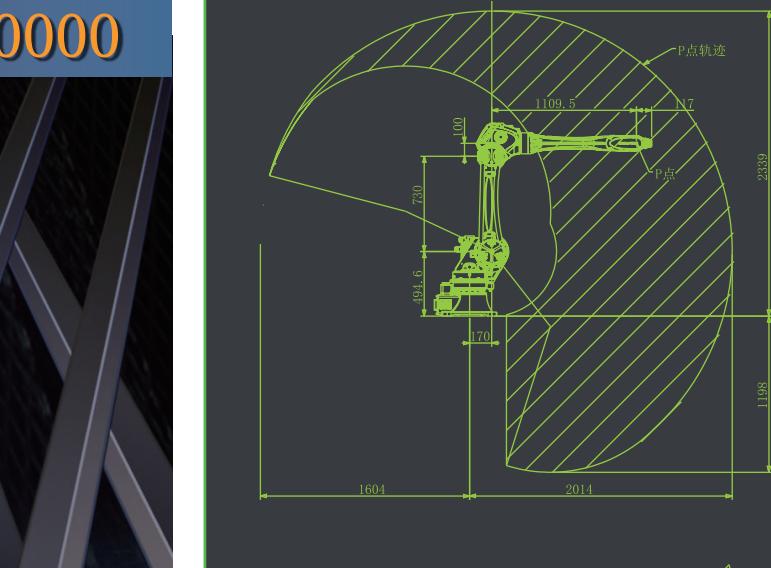
The protection grade reaches IP54 at the end and IP50 at the body.
Dust-proof and water-proof.
The repeat positioning accuracy is ±0.05mm.

主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS2110A	臂展Arm Length(mm)	地面-2轴距 494.6mm		2-3轴距 730mm		3-5轴距 1109.5mm	5轴-端面距 117mm	2100	10	±0.05	6	约230
	范围 Range(°)	±155°	-140°/+65°	-75°/+110°	±180°	±115°	±360°					
	最大速度 Max.Speed(°/s)	110°/s	146°/s	134°/s	273°/s	300°/s	336°/s					

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BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 200000

产品特点 Product Features

BRTIRUS2030A是伯朗特机器人股份有限公司针对多自由度复杂应用而开发的六轴工业机器人。其最大负载可达30KG, 拥有2058mm臂展, 六自由度的灵活性对注塑件取件、机床上下料、装配、搬运等场景能够应对自如。防护等级高—手腕IP54, 本体IP50, 防尘防水。精度高—重复定位精度±0.05mm。

BRTIRUS2030A is a six-axis robot developed by BORUNTE ROBOT Co.,Ltd. for complex applications with multiple degrees of freedom. The maximum load is 30KG and the maximum arm length is 2058mm. The flexibility of six degrees of freedom can be used to handle the scenes such as injection parts taking, machine loading and unloading, assembly and handling. The protection grade reaches IP54 at the end and IP50 at the body. Dust-proof and water-proof. The repeat positioning accuracy is ±0.05mm.

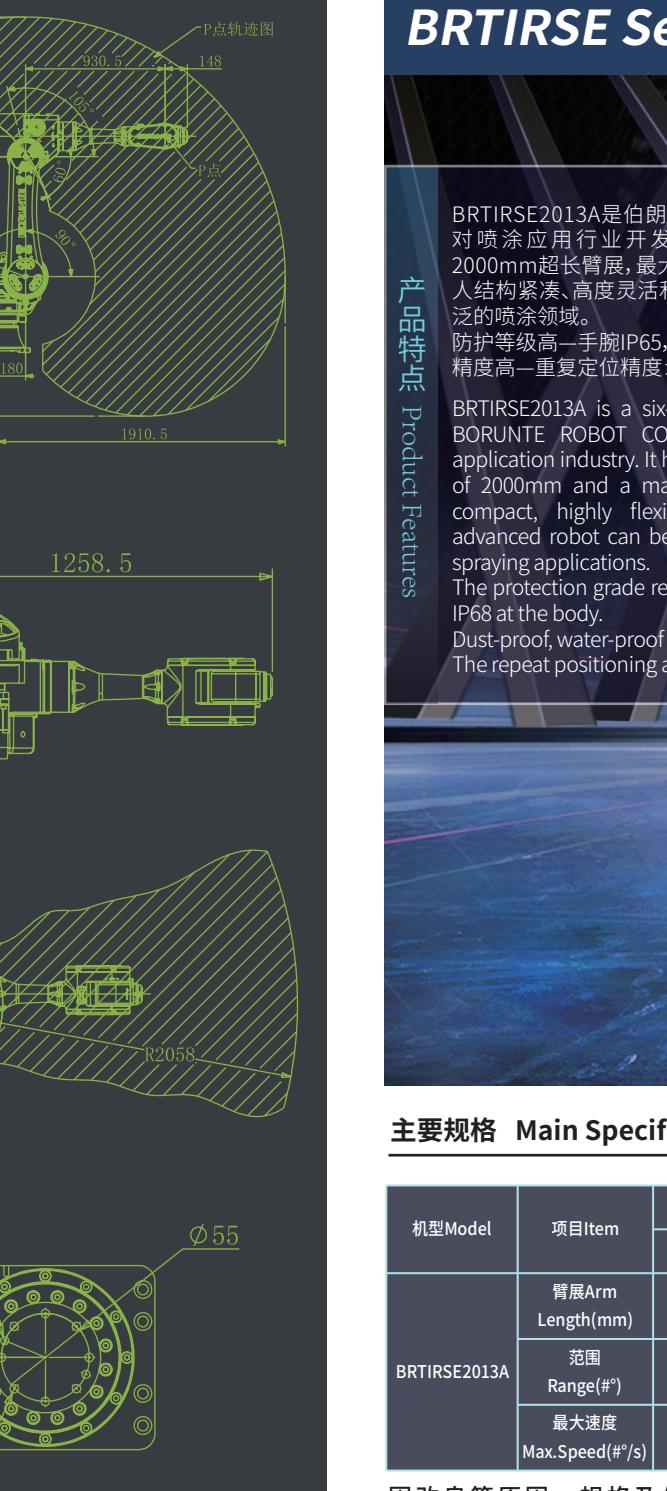


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS2030A	臂展Arm Length(mm)	地面-2轴距 540.6mm		2-3轴距 800mm		3-5轴距 930.5mm	5轴-端面距 148mm	2058	30	±0.05	10.16	约310
	范围 Range(°)	±150°	-90°/+70°	-55°/+105°	±180°	±115°	±360°					
	最大速度 Max.Speed(°/s)	102°/s	103°/s	123°/s	245°/s	270°/s	337°/s					

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机器人系列 Industrial Robot

BRTIRSE Series

六轴机器人
Six-axis Robot

¥ 285000

产品特点 Product Features

BRTIRSE2013A是伯朗特机器人股份有限公司针对喷涂应用行业开发的六轴机器人，其拥有2000mm超长臂展，最大负载可达13kg。该款机器人结构紧凑、高度灵活和技术先进，可以应用于广泛的喷涂领域。防护等级高—手腕IP65, 本体IP68, 防尘防水防爆。精度高—重复定位精度±0.5mm。

BRTIRSE2013A is a six-axis robot developed by BORUNTE ROBOT CO., LTD. for the spraying application industry. It has an ultra-long arm span of 2000mm and a maximum load of 13kg. The compact, highly flexible and technologically advanced robot can be used in a wide range of spraying applications. The protection grade reaches IP65 at the end and IP68 at the body. Dust-proof, water-proof and explosion-proof. The repeat positioning accuracy is ±0.5mm.

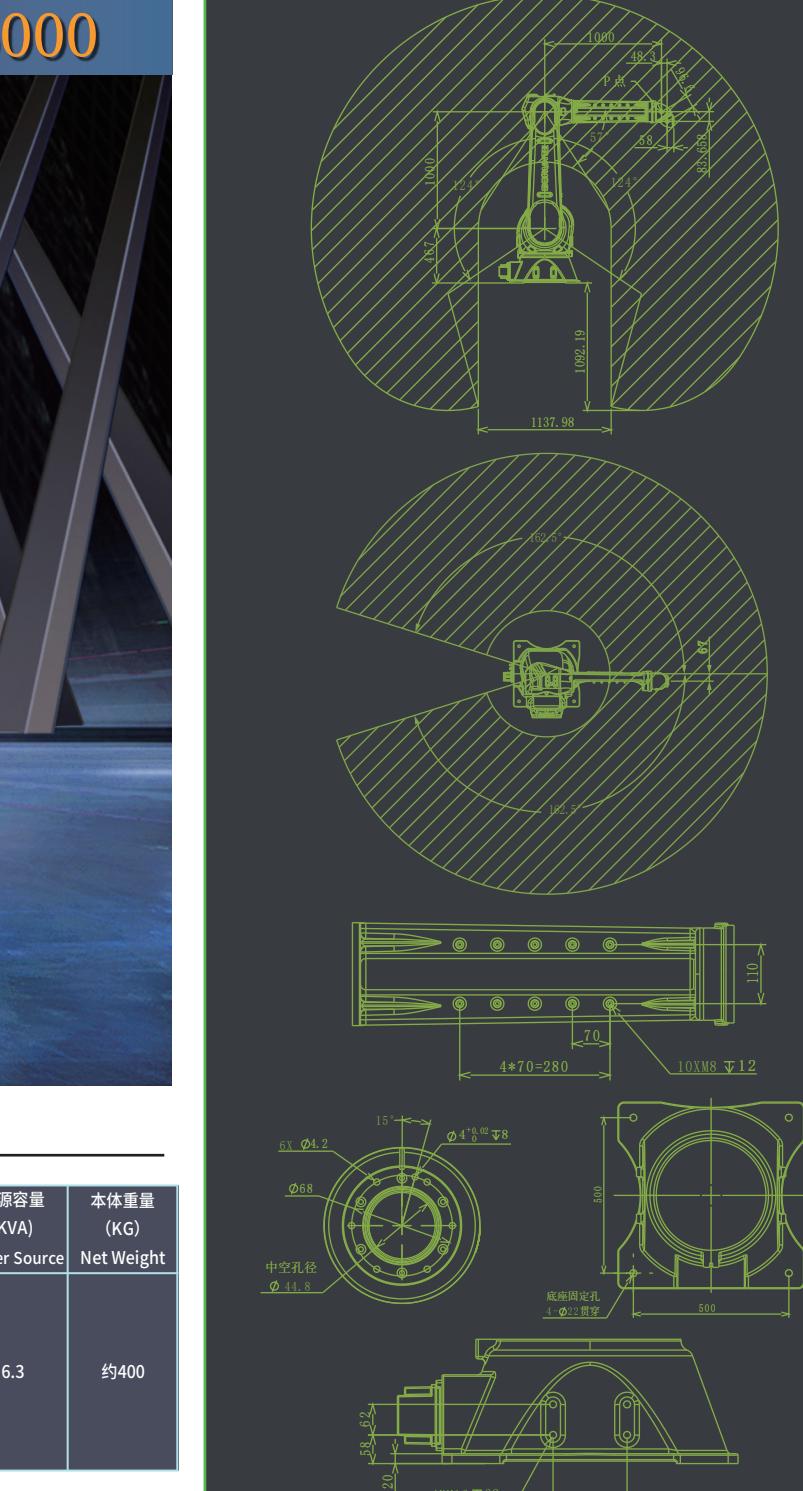


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRSE2013A	臂展Arm Length(mm)	地面-2轴距 467mm	/	2-3轴距 1000mm	3-5轴距 1000mm	5-6轴距 48.3mm	6轴-端面距 58mm	2000mm	13KG	±0.5mm	6.3	约400
	范围 Range(°)	±162.5°	±124°	-57°~+237°	±180°	±180°	±360°					
	最大速度 Max.Speed(°/s)	105°/s	105°/s	123°/s	473°/s	519°/s	613°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

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机器人系列 Industrial Robot

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 285000

产品特点 Product Features

BRTIRUS3030A六自由度工业机器人是一款通用型机器人，机器人的外形结构紧凑，各关节均安装了高精度减速机，高速的关节速度能进行灵活的作业，可以进行搬运、码垛、装配、注塑等作业，拥有灵活的安装方式。
防护等级高-手腕 IP54、本体 IP50,防尘防水。
精度高-重复定位精度±0.07mm。

BRTIRUS3030A six degrees of freedom industrial robot is a general robot, the robot has a compact shape and structure, each joint is installed with a high precision reducer, high speed joint speed can be flexible operation, can carry out handling, palletizing, assembly, injection molding and other operations, has a flexible installation mode. The protection grade reaches IP54 at the end and IP50 at the body.
Dust-proof and water-proof.
The repeat positioning accuracy is ±0.07mm.



主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量 (KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS3030A	臂展Arm Length(mm)	地面-2轴距 673mm		2-3轴距 1200mm		3-5轴距 1450mm	5轴-端面距 148mm	3000	30	±0.07	17.6	约830
	范围 Range(°#)	±160°	-105°/+60°	-75°/+115°	±180°	±120°	±360°					
	最大速度 Max.Speed(°#/s)	120°/s	120°/s	120°/s	245°/s	270°/s	337°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

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机器人系列 Industrial Robot

BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 200000

产品特点 Product Features

BRTIRUS2550A是伯朗特机器人股份有限公司针对多自由度的复杂应用而开发的一款六轴工业机器人，其拥有2550mm超长臂展，最大负载可达50kg。具有六个自由度的灵活性，对上下料、装配、注塑等场景能够应对自如。防护等级高-手腕IP54、本体IP50,防尘防水。
精度高-重复定位精度±0.1mm。

BRTIRUS2550A type robot is a six axis robot that developed for some monotonous, frequent and repetitive long-term operations or operations in dangerous and harsh environments. The maximum arm length is 2550mm. The maximum load is 50KG.it has six degrees of flexibility. Suitable for loading and unloading, assembling, molding,stacking etc.
The protection grade reaches IP54 at the end and IP50 at the body.
Dust-proof and water-proof.
The repeat positioning accuracy is ±0.1mm.

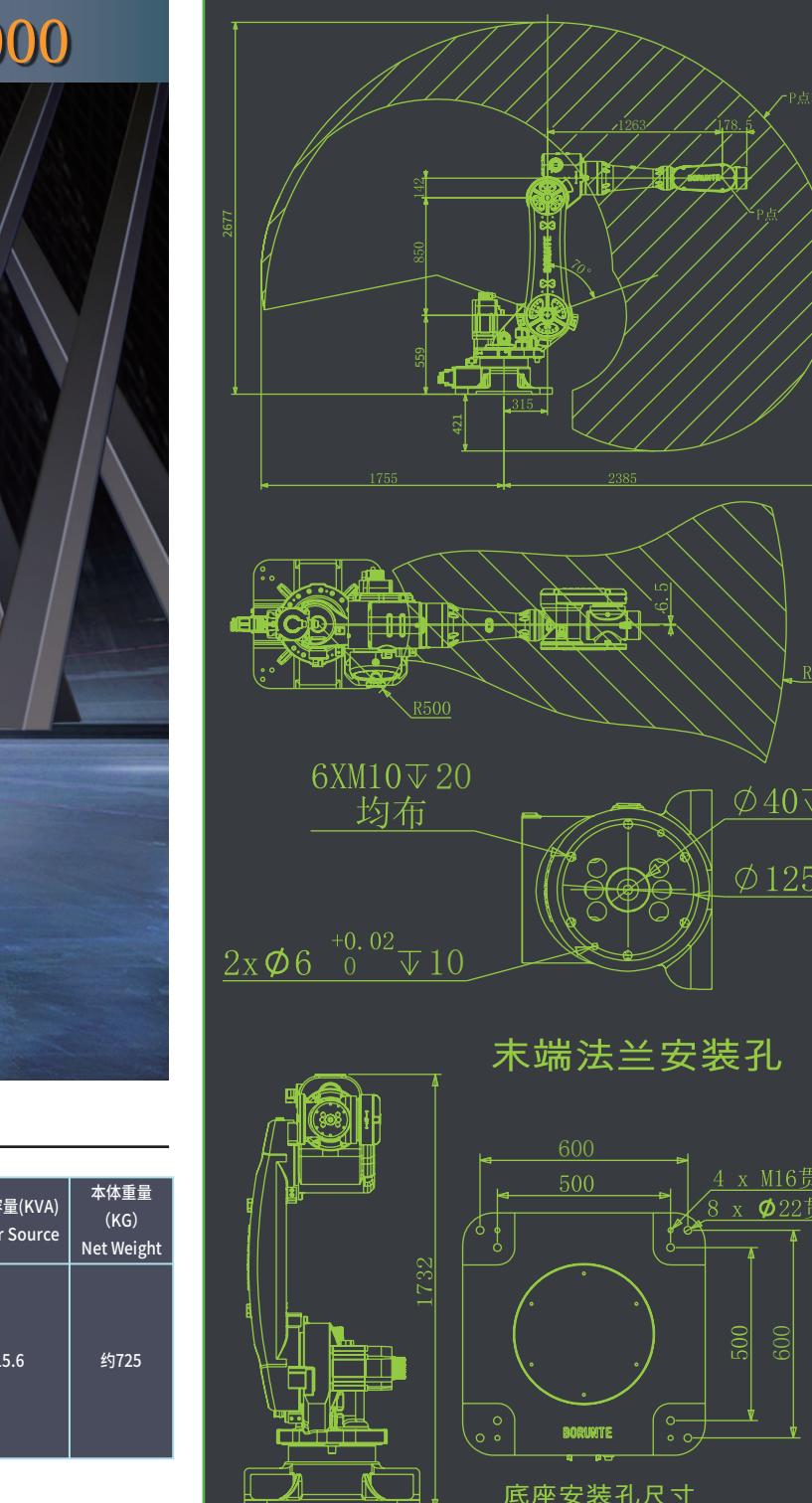


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS2550A	臂展Arm Length(mm)	地面-2轴距 559mm		2-3轴距 850mm		3-5轴距 1263mm	5轴-端面距 178.5mm	2550	50	±0.1	15.6	约725
	范围 Range(°#)	±160°	±70°	-75°/+115°	±180°	±125°	±360°					
	最大速度 Max.Speed(°#/s)	84°/s	52°/s	52°/s	245°/s	223°/s	223°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

Without further notice if specification and exterior have been changed because of improvement. Thanks for your understanding.



机器人系列 Industrial Robot

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BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 285000

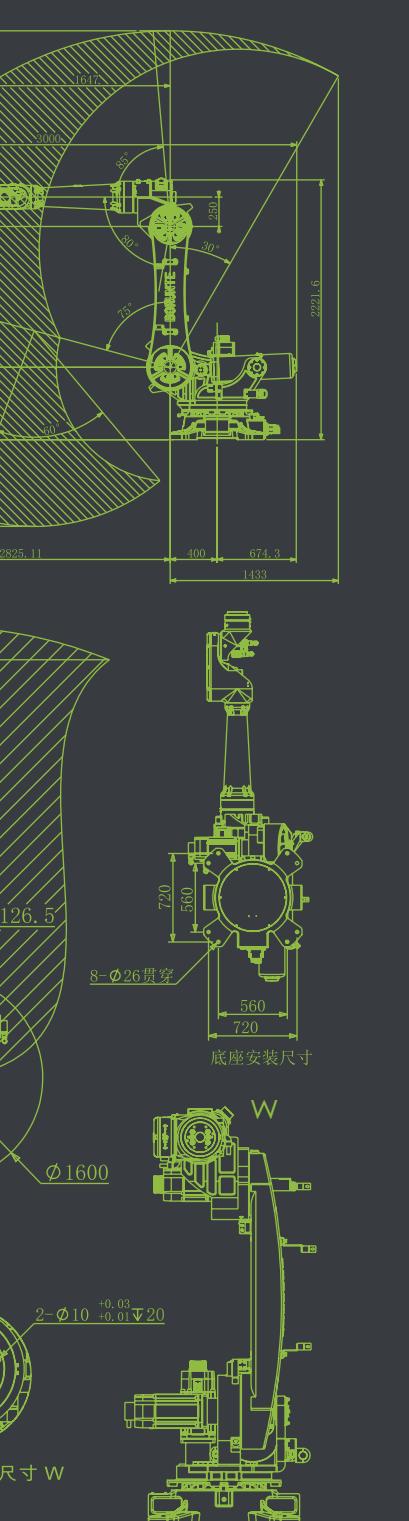


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS3511A	臂展 Arm Length(mm)			2-3轴距 1200mm	3-4轴距 250mm	3-5轴距 1647mm	5轴-端面距 277mm	3500	100	±0.2	28	约1350
	范围 Range(°)	±160°	-75°+30°	-80°+85°	±180°	±95°	±360°					
	最大速度 Max.Speed(°/s)	85°/s	70°/s	70°/s	82°/s	99°/s	124°/s					

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

Without further notice if specification and exterior have been changed because of improvement. Thanks for your understanding.



BRTIRUS Series

六轴机器人
Six-axis Robot

¥ 285000

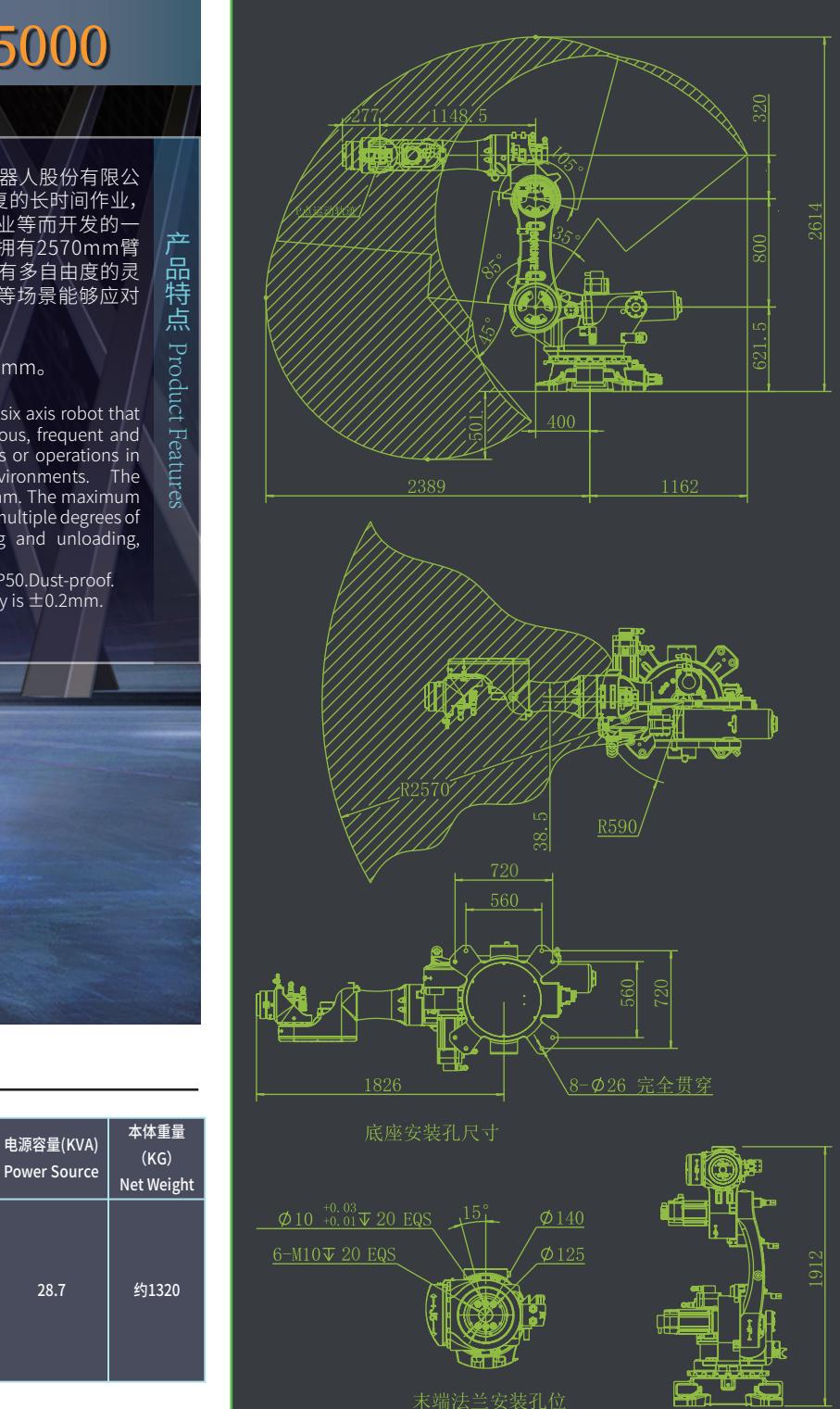


主要规格 Main Specification

机型 Model	项目 Item	手臂 Arm			手腕 Wrist			臂展(mm) Arm Length	负载(KG) Loading ability	重复定位精度 (mm) Repeatability	电源容量(KVA) Power Source	本体重量 (KG) Net Weight
		J1	J2	J3	J4	J5	J6					
BRTIRUS2520B	臂展 Arm Length(mm)			2-3轴距 800mm	3-4轴距 320mm	3-5轴距 1148.5mm	5轴-端面距 277mm	2570	200	±0.2	28.7	约1320
	范围 Range(°)	±160°	-85°+35°	-80°+105°	±180°	±95°	±360°					
	最大速度 Max.Speed(°/s)	57°/s	52°/s	52°/s	70°/s	75°/s	99°/s					

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BRTV Series

五轴伺服机械手
Five-axis servo Robot

BRTV09WDS5P0/F0

¥ 120000

BRTV13WDS5P0/F0

¥ 120000

产品特点 Product Features

BRTV09WDS5P0/F0, BRTV13WDS5P0/F0系列适用于120T-700T的各型卧式射出机的成品及水口取出,安装方式与传统式的横走式不同,是将成品与料头取出放置于射出机尾端,可以节省出机的安装空间。手臂形式双截式,双臂,上下行程900mm/1300mm,五轴AC伺服驱动,安装可节省射出机安装空间30-40%,更充分的利用厂房,并可增加产能(20-30%),降低产品的不良率,保障操作人员的安全性,减少人工,精准的控制生产量,减少浪费。

五轴驱控一体控制系统:信号线少,远距离通讯,扩展性能好,抗干扰能力强,重复定位精度高,可同时控制多轴,设备维护简单,故障率少。

BRTV09WDS5P0/F0, BRTV13WDS5P0/F0 series is applicable to all types of horizontal injection machine ranges of 120T-700T for take-out products and sprue. The installation direction is different from traditional beam robot, products are placed at the end of injection molding machines. It has double arm. Vertical arm is telescopic stage and vertical stroke is 900mm/1300mm. Five-axis AC servo drive. After install this robot can save 30-40% room to allow better utilization of production space. Furthermore, the productivity will be increased 20-30%, reduce the defective rate, ensure safety of operators, reduce manpower and accurately control the output to reduce waste.

Five-axis driver and controller integrated system: less connecting line, long distance communication, good expansion performance strong anti interference ability, high repeat precision, can simultaneously control multiple axis, simple equipment maintenance, low failure rate.



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended L.M.	驱动方式 Traverser Driven	治具型式 Model of EOAT	横行行程 (mm) Traverser Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (Nl/cycle) Air Consumption	净重 (KG) Net Weight
BRTV09WDS5P0/F0	3.5	120T-320T	AC伺服马达 AC Servo motor	两吸两拖 横行拱总长6米以内	待定	900	5	1.7	待定	9	3	非标准
BRTV13WDS5P0/F0	3.5	320T-700T	AC伺服马达 AC Servo motor	两吸两拖 横行拱总长6米以内	待定	1300	8	2.3	待定	9	3	非标准

机型表示: W: 双截式 D: 双臂机械手 (成品臂+料头臂) S5: 五轴AC伺服马达驱动 (成品臂/料头臂上下、引拔+横行)

Denote: W: Telescopic type. D: Product arm + runner arm. S5: Five-axis driven by AC Servo Motor.

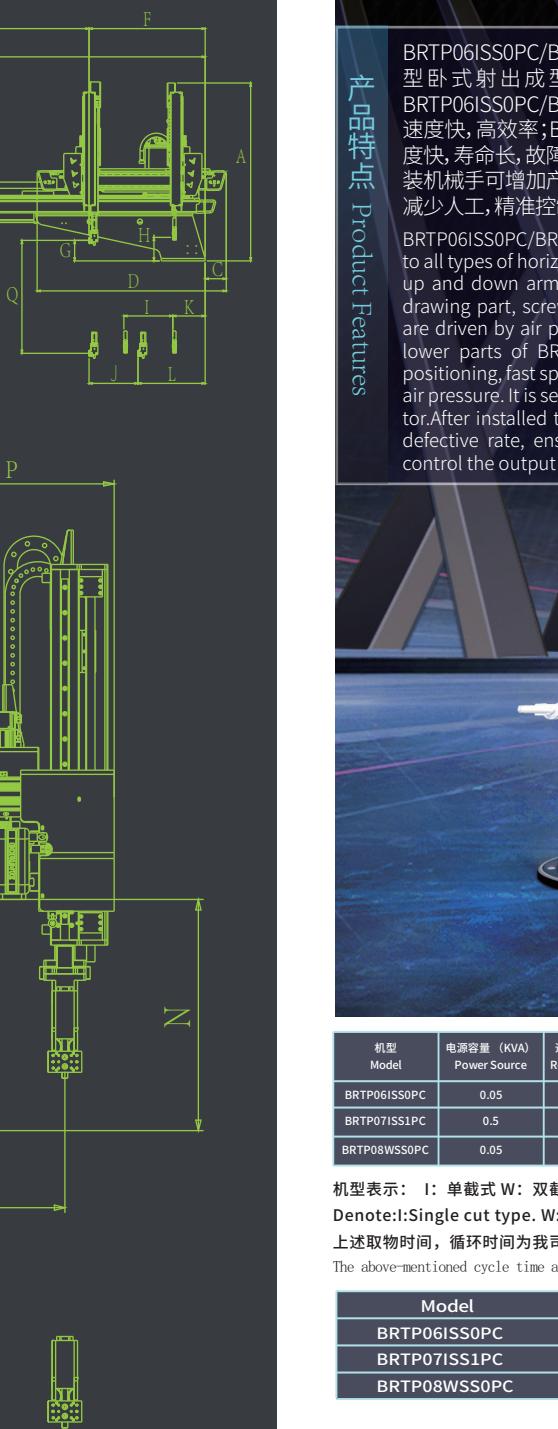
上述取物时间, 循环时间为我司内部测试标准测试结果, 在机器实际应用过程中会因实际使用行程, 负载, 调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q
BRTV09WDS5P0/F0	1555	横行拱总长6米以内	160	待定	待定	174	187	187	待定	待定	126	266	待定	549	484	待定	900
BRTV13WDS5P0/F0	1614	横行拱总长6米以内	162	待定	待定	167.5	191	待定	待定	253.5	399	待定	549	481	待定	1300	

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BRTP Series

斜臂式/一轴伺服机械手
Swing-arm /One-axis servo Robot

BRTP06ISS0PC

¥ 14250

BRTP07ISS1PC

¥ 14250

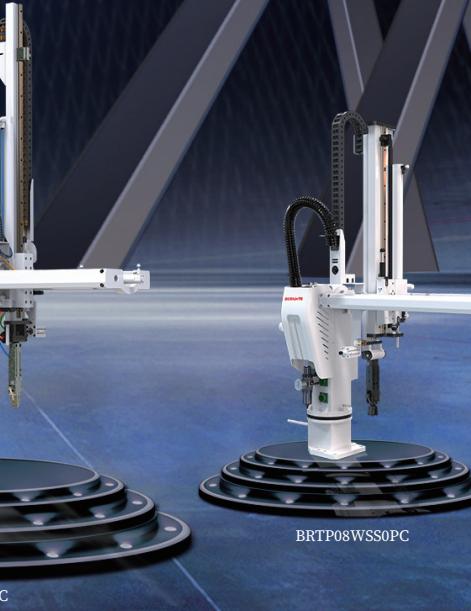
BRTP08WSS0PC

¥ 14250

产品特点 Product Features

BRTP06ISS0PC/BRTP07ISS1PC/BRTP08WSS0PC机型适用于30T-250T的各型卧式射出成型机的成品取出,上下手臂为单截式/双截式,其中BRTP06ISS0PC/BRTP08WSS0PC的上下、引拔、旋出、旋入均采用气压驱动,速度快,高效率;BRTP07ISS1PC的上下采用AC伺服马达驱动,定位精准,速度快,寿命长,故障低,其余部位采用气压驱动,是几款经济实惠型机械手。安装机械手可增加产能(10-30%)降低产品的不良率,保障操作人员的安全性,减少人工,精准控制生产量,减少浪费。

BRTP06ISS0PC/BRTP07ISS1PC/BRTP08WSS0PC swing-arm robot is applicable to all types of horizontal injection machine of 30T-250T for take-out products. The up and down arm is single/double sectional type. The upper and lower part, drawing part, screwing out and screwing in of BRTP06ISS0PC/BRTP08WSS0PC are driven by air pressure, with high speed and high efficiency; The upper and lower parts of BRTP07ISS1PC are driven by AC servo motor, with accurate positioning, fast speed, long service life and low fault. The rest parts are driven by air pressure. It is several economical manipulators. It is an economical manipulator. After installed this robot, the productivity will be increased 10-30%, reduce defective rate, ensure safety of operators, reduce manpower and accurately control the output to reduce waste.



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended L.M.	驱动方式 Traverser Driven	治具型式 Model of EOAT	横行行程 (mm) Traverser Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	放出角度 (degree) Swing Angle	空气消耗量 (Nl/cycle) Air Consumption	净重 (KG) Net Weight
BRTP06ISS0PC	0.05	30T-150T	气缸驱动	/	120	650	2	1.6	5.5	30-90	3	36	
BRTP07ISS1PC	0.5	60T-200T	AC伺服马达、气缸	零吸零拖	/	125	750	2	1.4	5	30-90	3	50
BRTP08WSS0PC	0.05	150T-250T	气缸驱动	零吸零拖	/	300	850	2	2	6	30-90	3	60

机型表示: I: 单截式 W: 双截式 S: 双臂机械手 (成品臂) S0: 斜臂气缸驱动 (成品臂上下) S1: 一轴AC伺服马达驱动 (成品臂/料头臂上下)

Denote:I:Single cut type. W:Telescopic type. S: Product arm.S0: Driven by cylinder. S1:One-axis driven by AC Servo Motor.

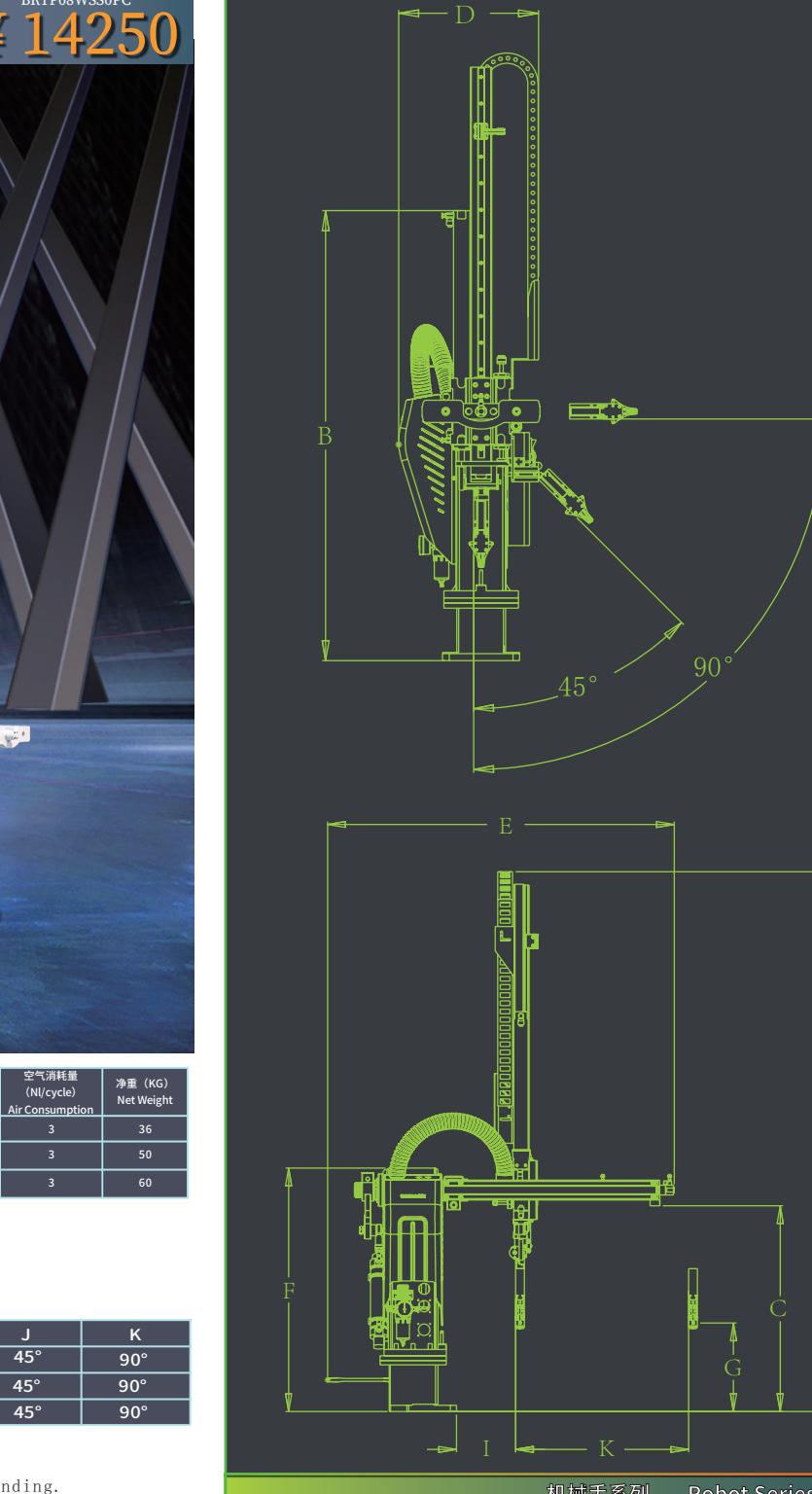
上述取物时间, 循环时间为我司内部测试标准测试结果, 在机器实际应用过程中会因实际使用行程, 负载, 调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K
BRTP06ISS0PC	1372	1225	530	316	881	619	50	440	225	45°	90°
BRTP07ISS1PC	1577	/	523	462.5	1122	861	118	360	219	45°	90°
BRTP08WSS0PC	1205	1031	523	365	972	619	102	300	183	45°	90°

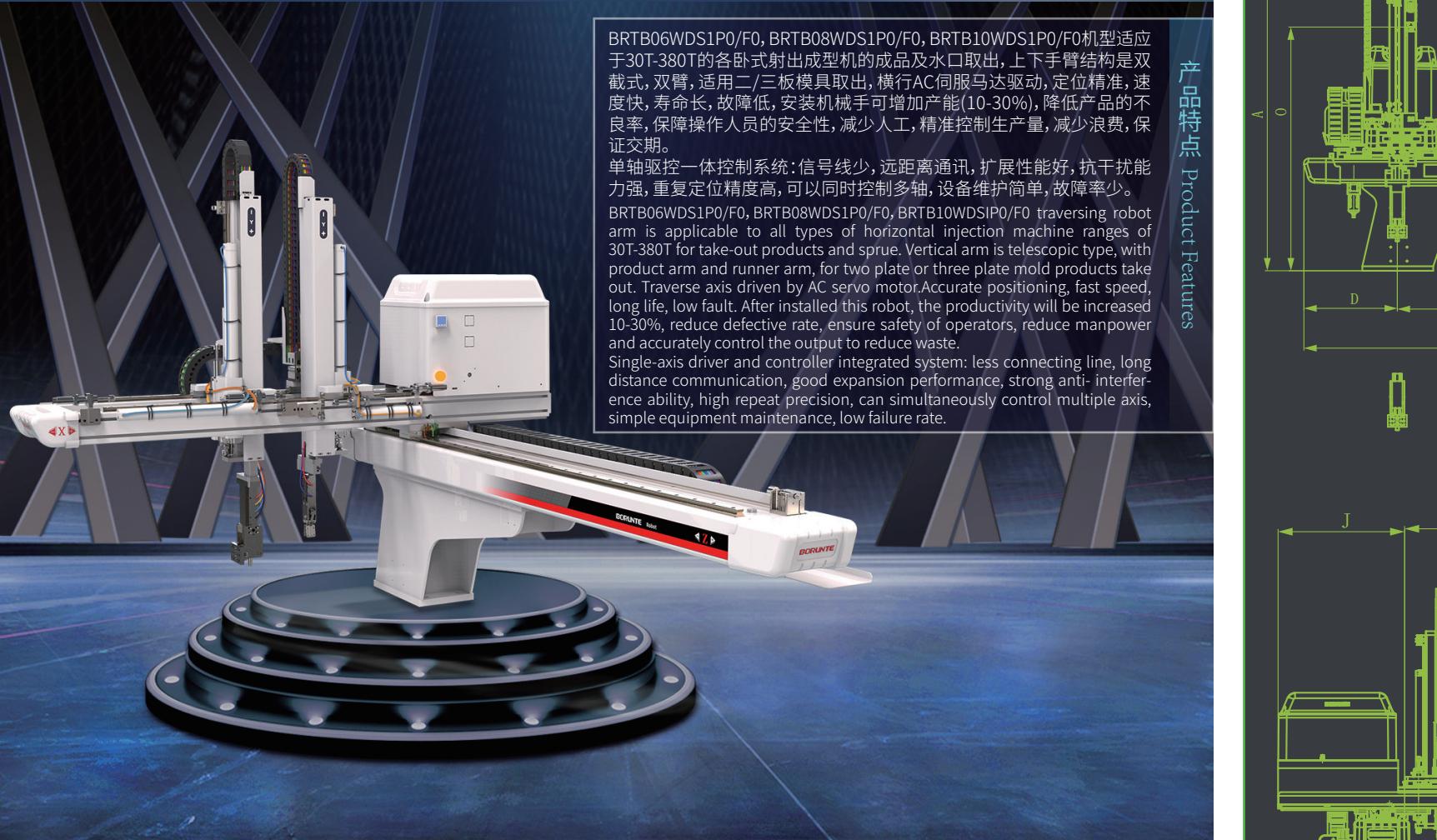
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BRTB Series

一轴伺服机械手
One-axis servo Robot



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTB06WDS1P0/F0	0.5	30T-120T	AC伺服马达 AC Servo motor	一吸一拖	1100	P:200 R:125	600	3	1.6	5.8	3.5	175
BRTB08WDS1P0/F0	0.5	120T-250T	AC伺服马达 AC Servo motor	一吸一拖	1250	P:300 R:125	800	3	1.7	6.49	3.5	198
BRTB10WDS1P0/F0	0.9	250T-380T	AC伺服马达 AC Servo motor	一吸一拖	1600	P:300 R:125	1000	3	1.92	8.16	4.2	221

机型表示: W: 双截式 D: 双臂机械手 (成品臂+料头臂) S1: 横行AC伺服马达驱动

Denote: W: Telescopic type D: Product arm + runner arm S1: AC Servo driven on traverse axis

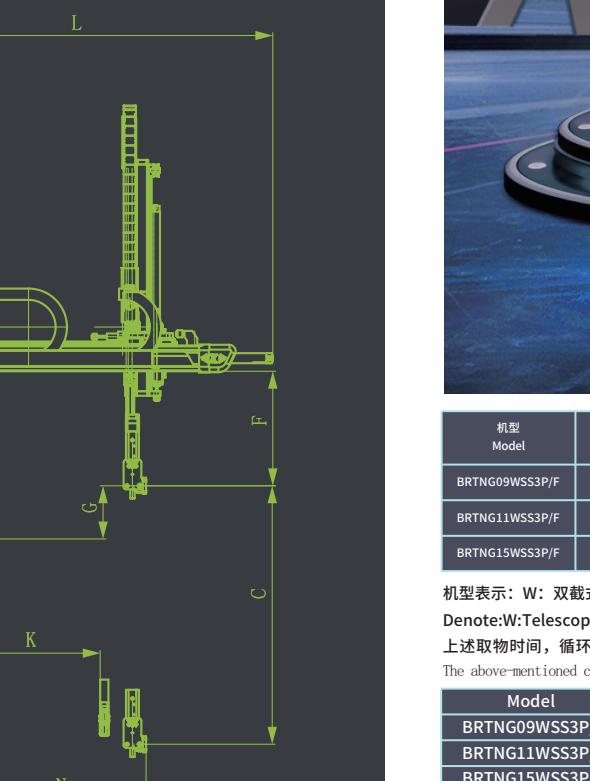
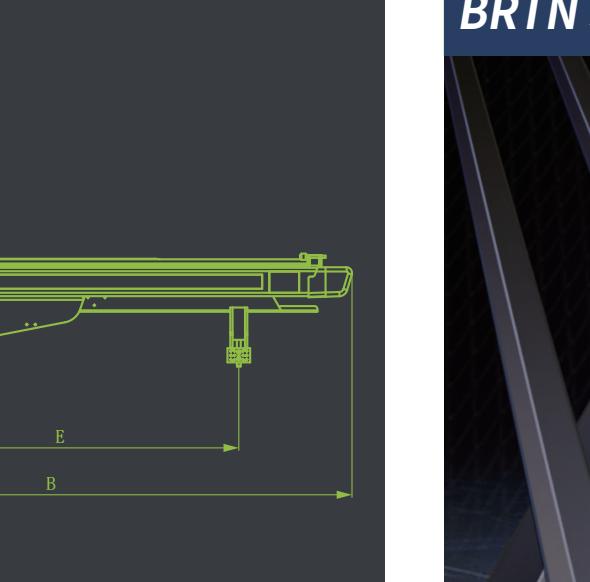
上述取物时间, 循环时间为我司内部测试标准测试结果, 在机器实际应用过程中会因实际使用行程, 负载, 调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
BRTB06WDS1P0/F0	1200	1900	600	403	1100	355	165	210	110	475	365	1000	242	365	933
BRTB08WDS1P0/F0	1340	2061	800	403	1250	355	165	210	135	475	520	1190	225	520	1033

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机械手系列 Robot Series

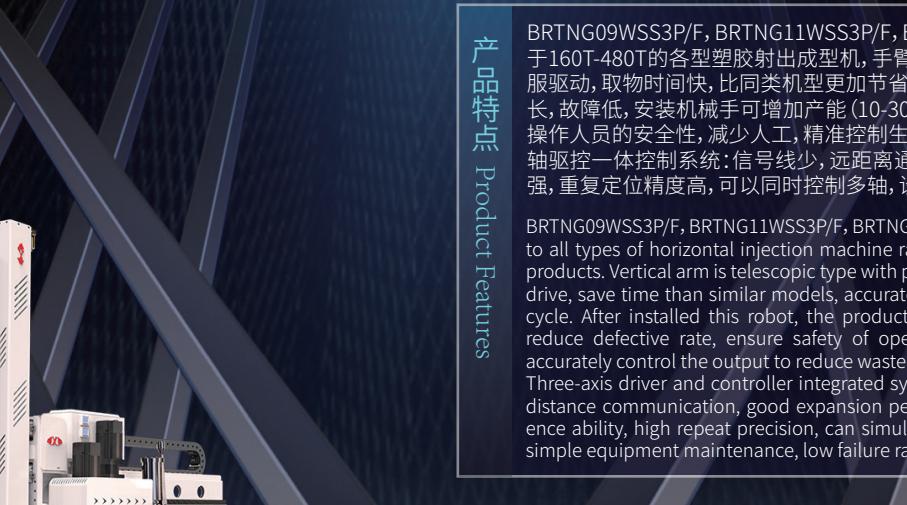
BRTN Series

三轴伺服机械手
Three-axis servo Robot

¥ 60000

¥ 60000

¥ 90000



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTNG09WSS3P/F	3.2	160T-380T	AC伺服马达 AC Servo motor	两吸两拖	1500	600	950	2	0.68	4.07	3.2	300
BRTNG11WSS3P/F	3.2	250T-480T	AC伺服马达 AC Servo motor	两吸两拖	1700	700	1100	2	0.87	4.42	3.2	305
BRTNG15WSS3P/F	3.2	470T-800T	AC伺服马达 AC Servo motor	两吸两拖	2200	900	1500	3	1.5	7.02	3.2	680

机型表示: W: 双截式 S:单臂机械手 (成品臂) S3: 三轴AC伺服马达驱动 (成品臂上下、引拔+横行)

Denote: W: Telescopic stage. S:Product arm S3:Three-axis driven by AC Servo Motor(Traverse-axis, Vertical-axis+Crosswise-axis)

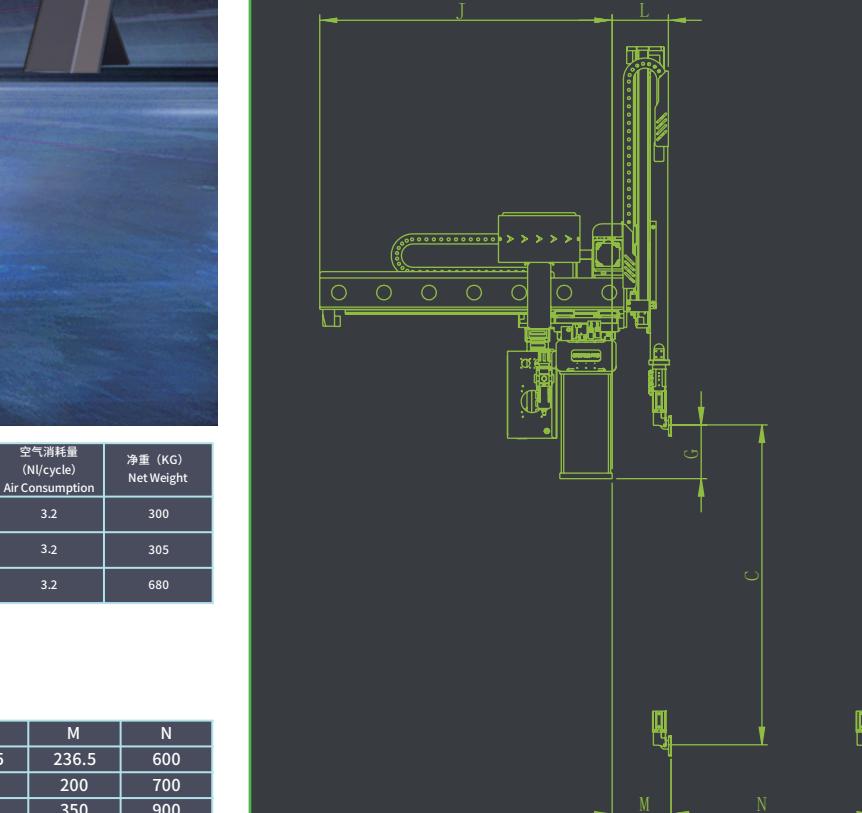
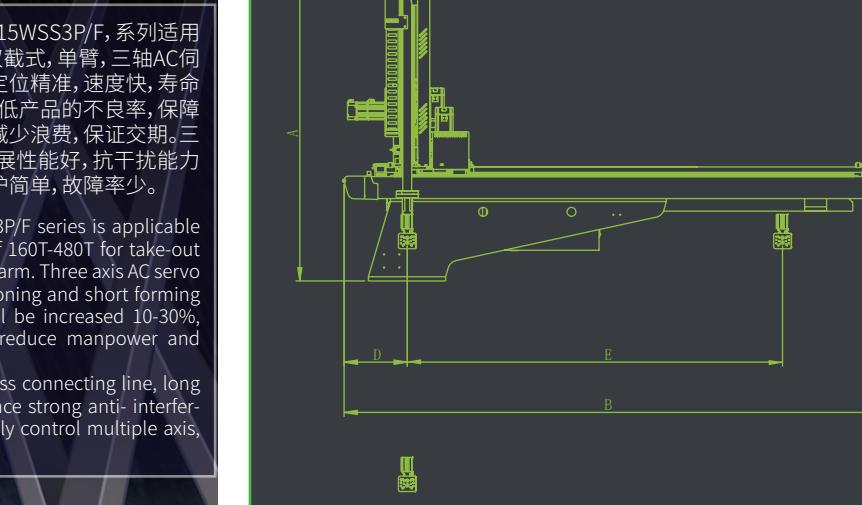
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The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTNG09WSS3P/F	1362	2275.5	950	298	1500	/	219	/	/	916	/	232.5	236.5	600
BRTNG11WSS3P/F	1485	2510	1100	295	1700	/	185	/	/	1006	/	193	200	700
BRTNG15WSS3P/F	1751	3075	1500	357	2200	/	183	/	/	1396	/	344	350	900

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机械手系列 Robot Series

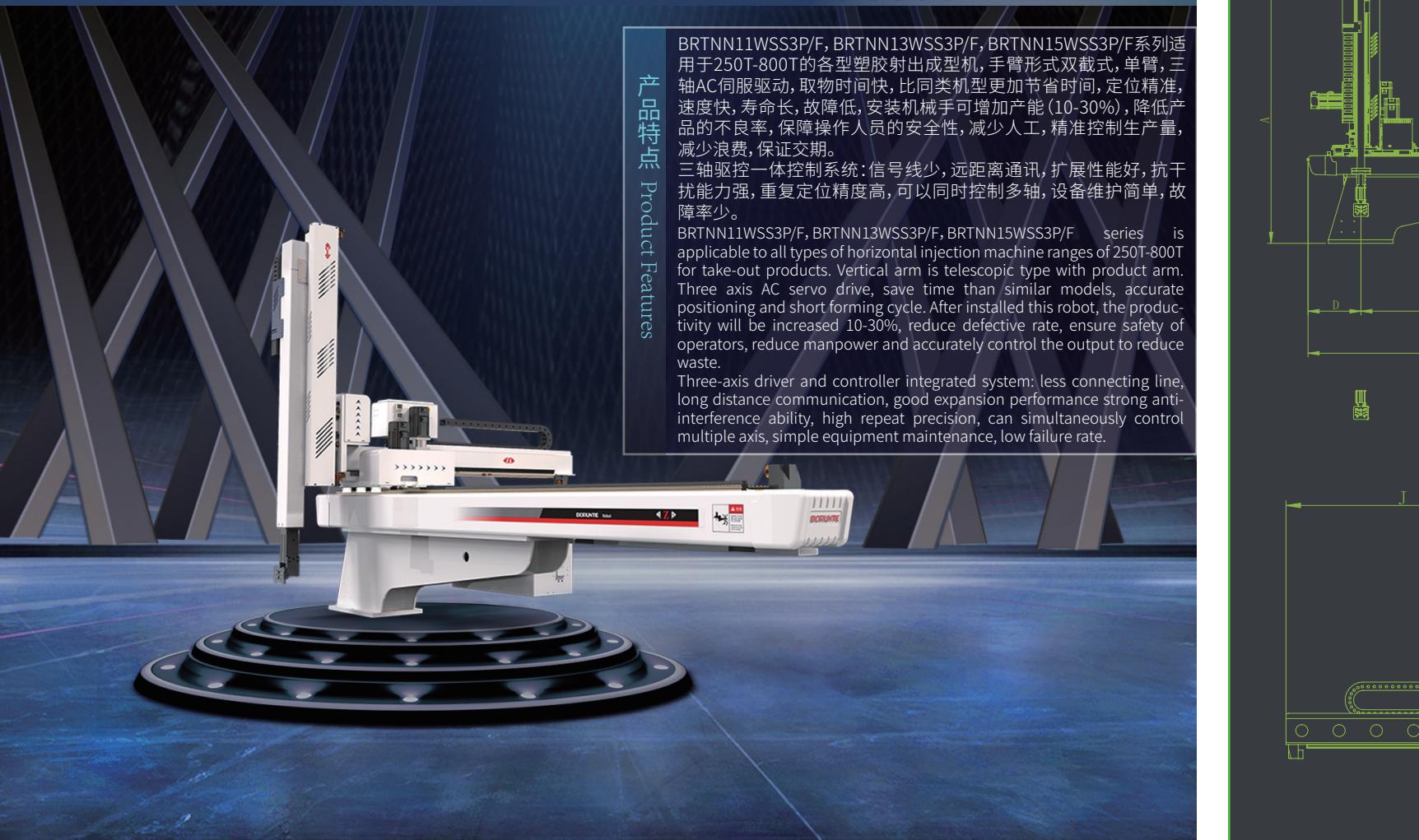
BRTN Series

三轴伺服机械手
Three-axis servo Robot

BRTNN11WSS3P/F
¥ 60000

BRTNN13WSS3P/F
¥ 90000

BRTNN15WSS3P/F
¥ 90000



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTNN11WSS3P/F	3.2	250T-480T	AC伺服马达 AC Servo motor	两吸两抱	1700	700	1100	10	1.63	6.15	3.2	305
BRTNN13WSS3P/F	3.2	470-700T	AC伺服马达 AC Servo motor	两吸两抱	1840	800	1300	10	2.6	8.9	3.2	660
BRTNN15WSS3P/F	3.2	470T-800T	AC伺服马达 AC Servo motor	两吸两抱	2200	900	1500	15	2.74	9.03	3.2	680

机型表示：W: 双截式 S:单臂机械手（成品臂）. S3: 三轴AC伺服马达驱动（成品臂上下、引拔+横行）

Denote: W: Telescopic type. S: Product arm S3: Three-axis driven by AC Servo Motor(Traverse-axis, Vertical-axis+Crosswise-axis)

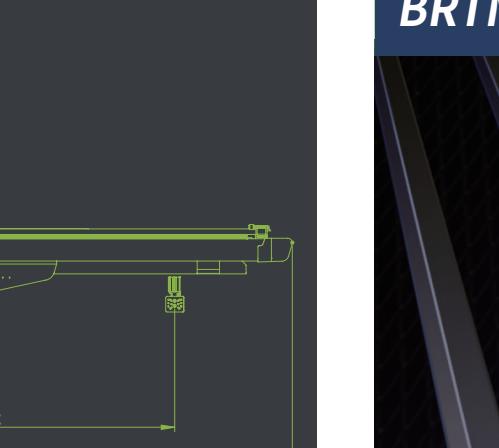
上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTNN11WSS3P/F	1485	2510	1100	295	1700	/	181	/	/	1006	/	193	215	700
BRTNN13WSS3P/F	1681.5	2695	1300	357	1840	/	184.5	/	/	1299	/	326	330	800
BRTNN15WSS3P/F	1751	3075	1500	357	2200	/	183	/	/	1396	/	344	350	900

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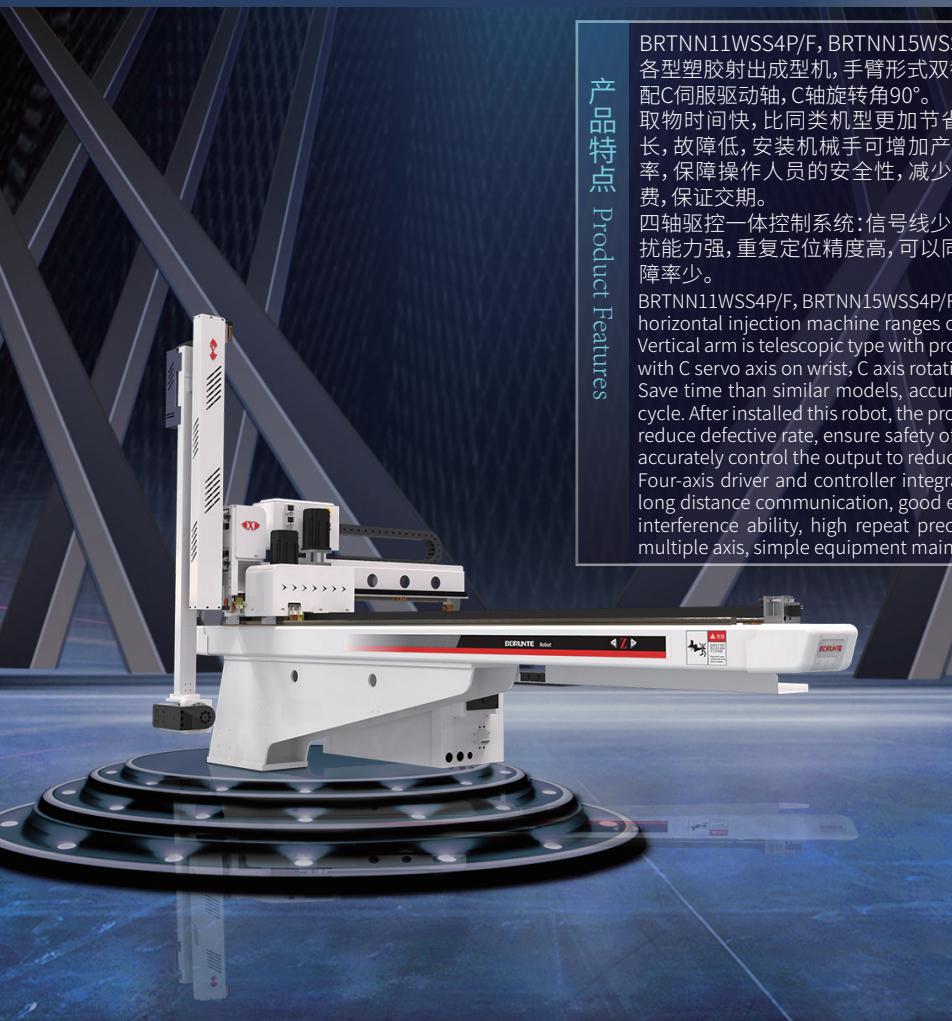


BRTN Series

四轴伺服机械手
Four-axis servo Robot

BRTNN11WSS4P/F
¥ 90000

BRTNN15WSS4P/F
¥ 120000



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTNN11WSS4P/F	3.4	250T-480T	AC伺服马达 AC Servo motor	两吸两抱	1700	700	1100	10	1.63	6.15	3.2	305
BRTNN15WSS4P/F	3.4	470T-800T	AC伺服马达 AC Servo motor	两吸两抱	2200	900	1500	15	2.74	9.03	3.2	680

机型表示：W: 双截式 S:单臂机械手（成品臂）S4: 四轴AC伺服马达驱动（成品臂上下、C轴、引拔+横行）

Denote: W: Telescopic type. S: Product arm S4: Four-axis driven by AC Servo Motor(Traverse-axis, C-axis, Vertical-axis+Crosswise-axis)

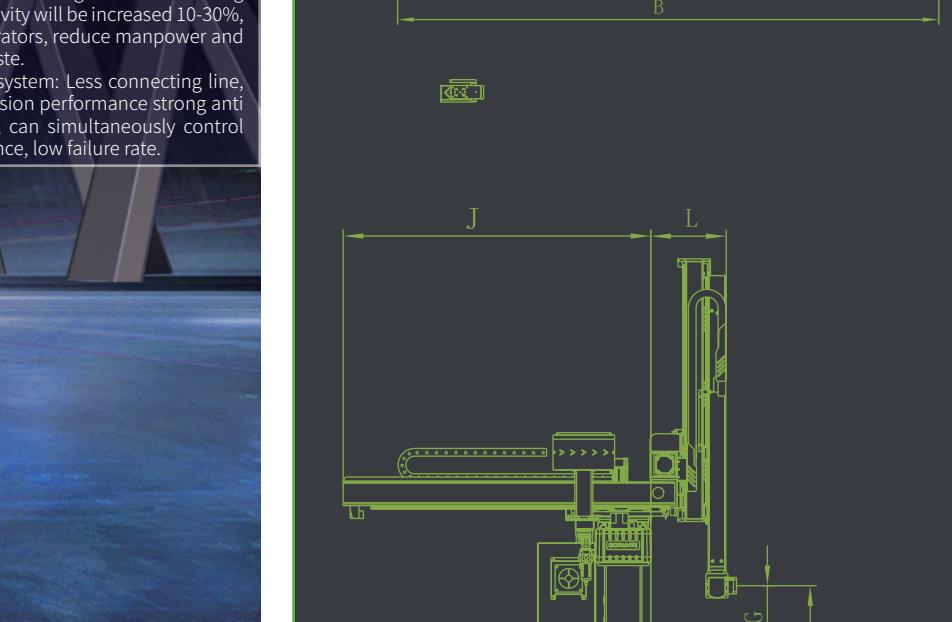
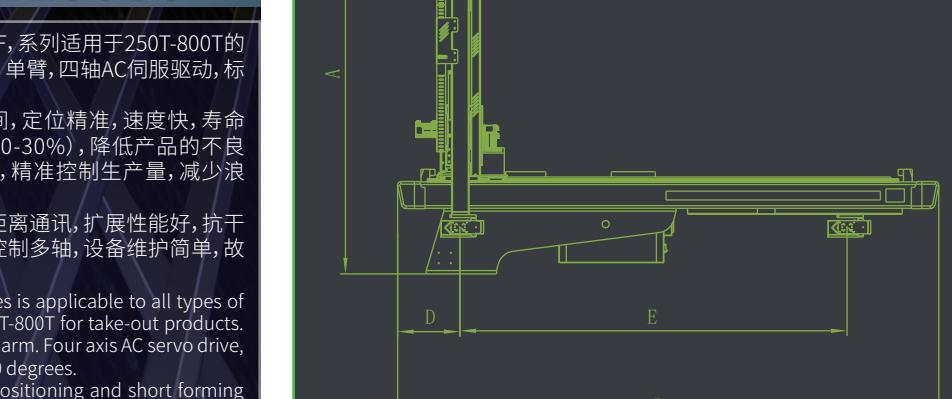
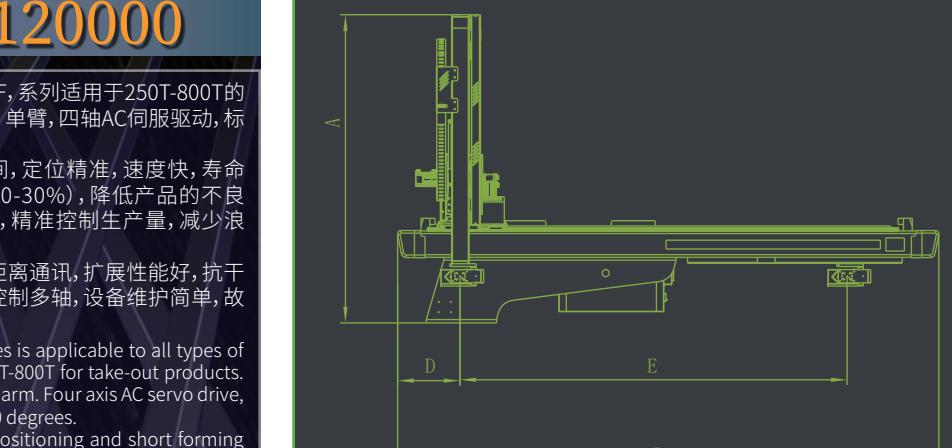
上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTNN11WSS4P/F	1485	2510	1100	293	1700	/	164	/	/	1001	/	208	265	700
BRTNN15WSS4P/F	1751	3075	1500	357	2200	/	170.5	/	/	1398.5	/	368	417	900

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

Without further notice if specification and exterior have been changed because of improvement. Thanks for your understanding.



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTNN11WSS4P/F	3.4	250T-480T	AC伺服马达 AC Servo motor	两吸两抱	1700	700	1100	10	1.63	6.15	3.2	305
BRTNN15WSS4P/F	3.4	470T-800T	AC伺服马达 AC Servo motor	两吸两抱	2200	900	1500	15	2.74	9.03	3.2	680

机型表示：W: 双截式 S:单臂机械手（成品臂）S4: 四轴AC伺服马达驱动（成品臂上下、C轴、引拔+横行）

Denote: W: Telescopic type. S: Product arm S4: Four-axis driven by AC Servo Motor(Traverse-axis, C-axis, Vertical-axis+Crosswise-axis)

上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTNN11WSS4P/F	1485	2510	1100	293	1700	/	164	/	/	1001	/	208	265	700
BRTNN15WSS4P/F	1751	3075	1500	357	2200	/	170.5	/	/	1398.5	/	368	417	900

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

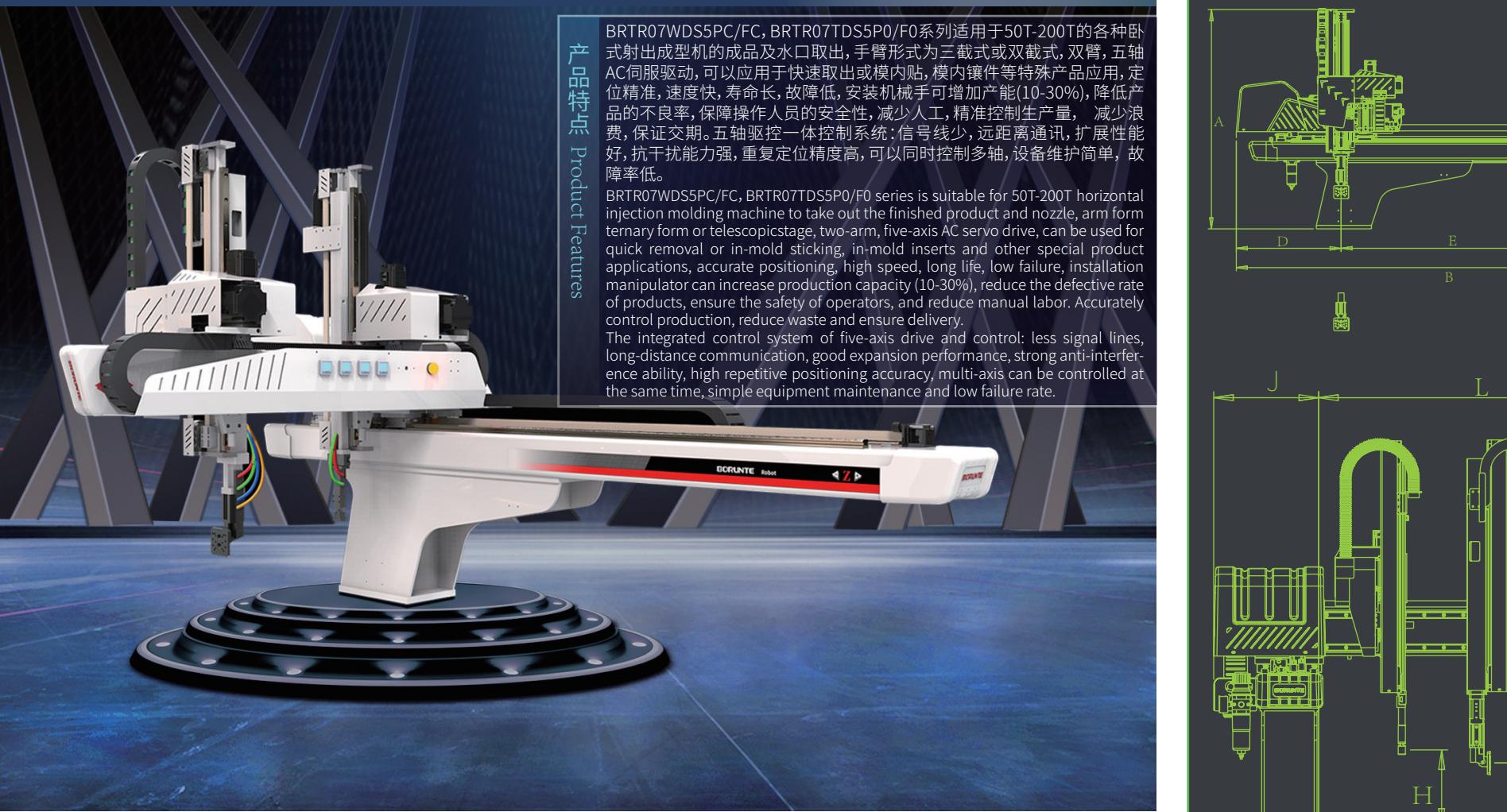
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BRTR Series

五轴伺服机械手
Five-axis servo Robot

BRTR07WDS5PC/FC
¥ 80000

BRTR07TDS5P0/F0
¥ 90000



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M.	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (Nl/cycle) Air Consumption	净重 (KG) Net Weight
BRTR07WDS5PC/FC	3.5	50T-200T	AC伺服马达 AC Servo motor	四吸两抱	1300	P:300 R:125	720	3	1.02	4.75	4	270
BRTR07TDS5P0/F0	3.2	50T-160T	AC伺服马达 AC Servo motor	两吸两抱	1300	P:310 R:310	700	3	0.92	4.55	4	270

机型表示: W: 双截式 T: 三截式 D: 双臂机械手 (成品臂+料头臂) S5: 五轴AC伺服马达驱动 (成品臂/料头臂上下、引拔+横行)

Denote: W: Telescopic stage. T: ternary form D:Product arm + runner arm. S5: Five-axis driven by AC Servo Motor.

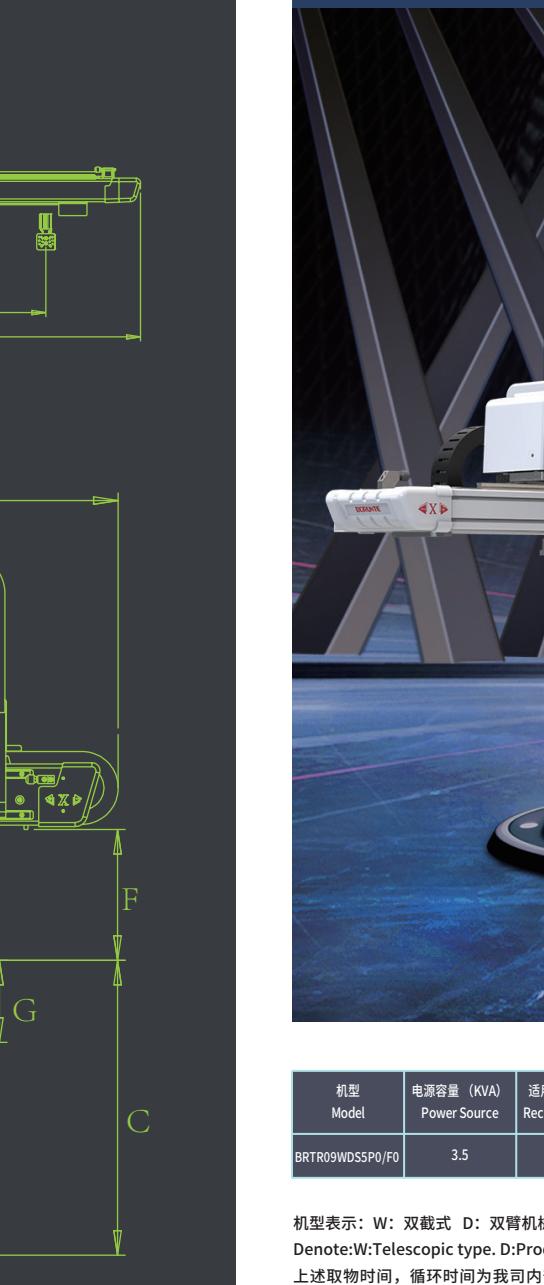
上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTR07WDS5PC/FC	1200	2280	720	570	1300	310	200	240	90	322	125	1020	325	300
BRTR07TDS5P0/F0	875	2250	700	614	1300	240	100	80	122.5	350	310	952.5	289.5	310

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

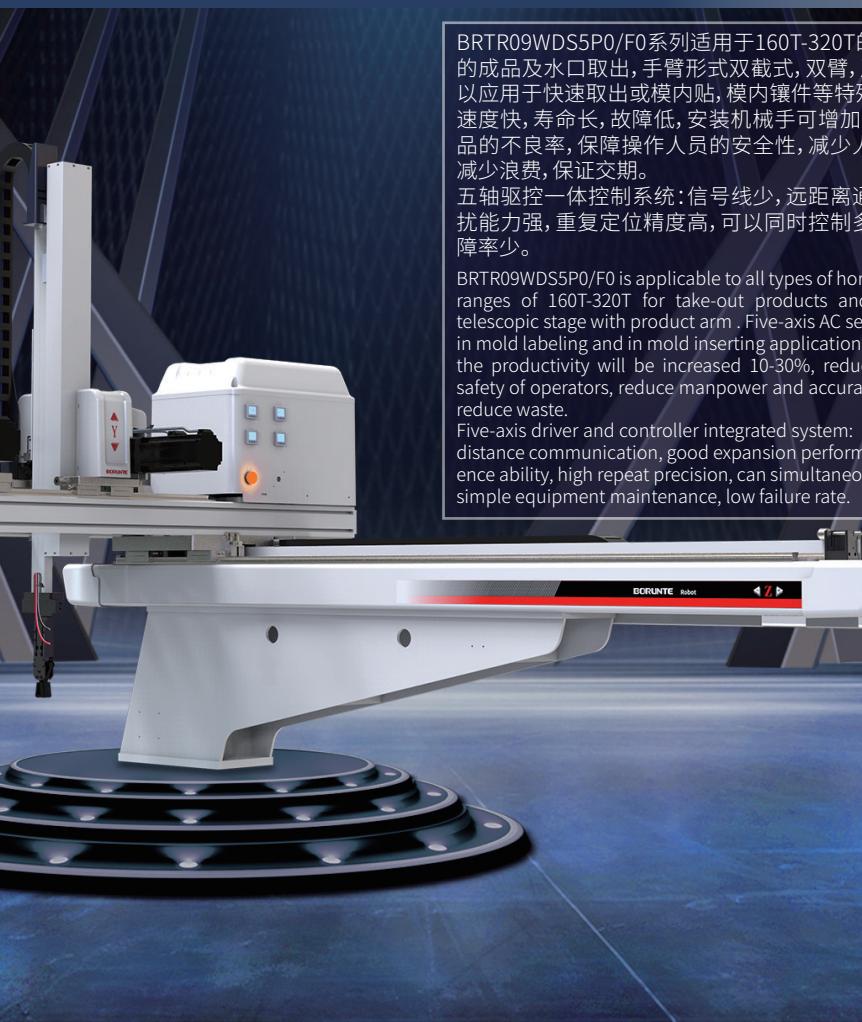
Without further notice if specification and exterior have been changed because of improvement. Thanks for your understanding.



BRTR Series

五轴伺服机械手
Five-axis servo Robot

¥ 57000



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M.	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (Nl/cycle) Air Consumption	净重 (KG) Net Weight
BRTR09WDS5P0/F0	3.5	160T-320T	AC伺服马达 AC Servo motor	四吸两抱	1500	P:550 R:550	950	8	1.5	7.03	4	300

机型表示: W: 双截式 D: 双臂机械手 (成品臂+料头臂) S5: 五轴AC伺服马达驱动 (成品臂/料头臂上下、引拔+横行)

Denote: W: Telescopic type. D: Product arm + runner arm. S5: Five-axis driven by AC Servo Motor.

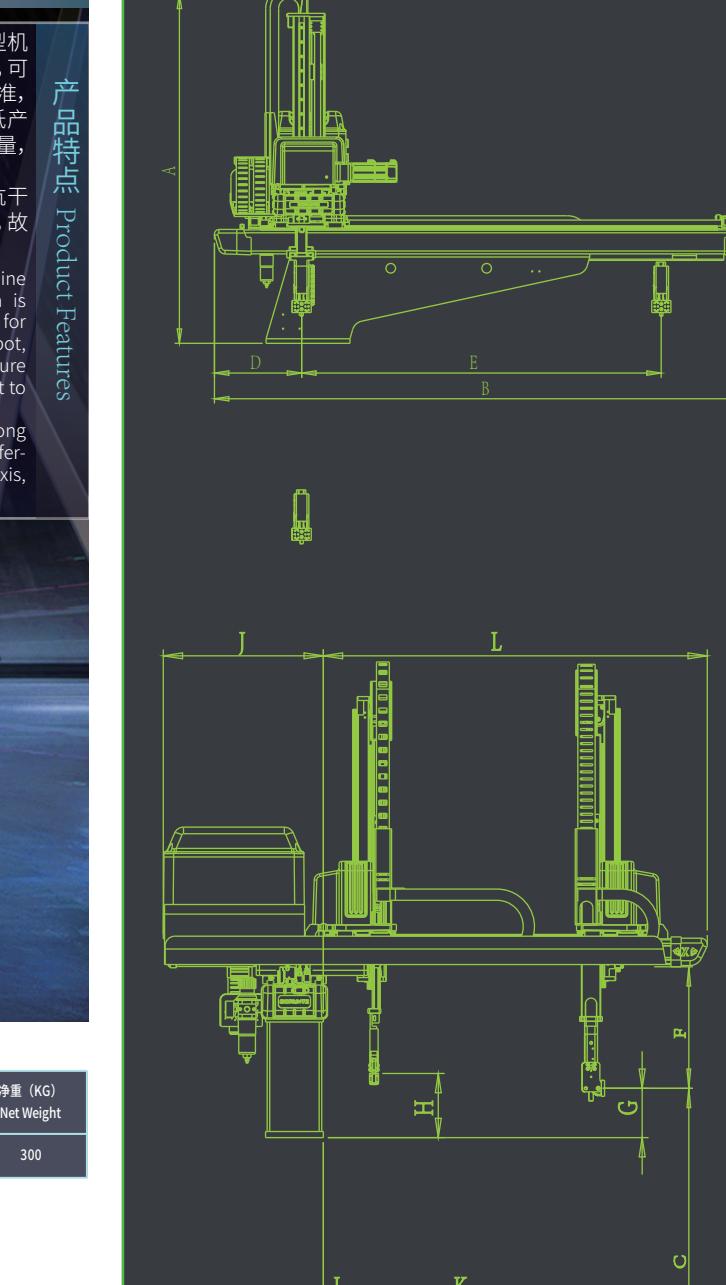
上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTR09WDS5P0/F0	1480	2280	950	365	1500	375	153	196	140	500	550	1195	330	550

因改良等原因，规格及外观有所变更时，不再另行通知，敬请谅解。

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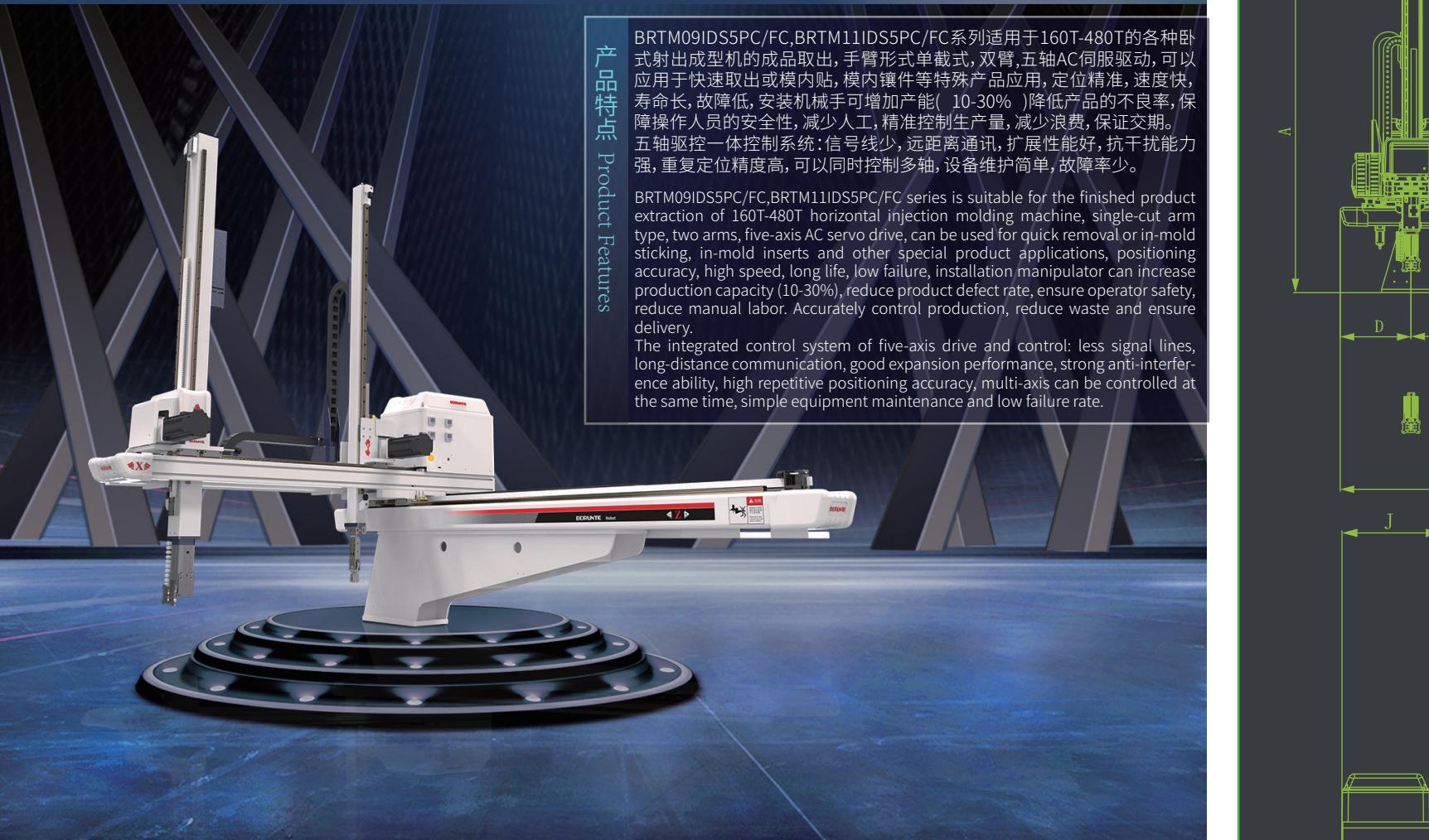


BRTM Series

五轴伺服机械手
Five-axis servo Robot

BRTM09IDS5PC/FC
¥ 90000

BRTM11IDS5PC/FC
¥ 90000



机型 Model	电源容量 (KVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTM09IDS5PC/FC	3.5	160T-320T	AC伺服马达 AC Servo motor	两吸四拖 Two-suction four-pull	1500	P:650 R:650	900	10	2.74	7.60	4	310
BRTM11IDS5PC/FC	4.1	320T-480T	AC伺服马达 AC Servo motor	两吸四拖 Two-suction four-pull	1700	P:770 R:770	1100	15	3.04	8.50	4	325

机型表示：I: 单截式 D:双臂机械手（成品臂+料头臂） S5: 五轴AC伺服马达驱动（成品臂/料头臂上下、引拔+横行）

Denote:I:Single cut type. D:Product arm + runner arm.S5:Five-axis driven by AC Servo Motor.

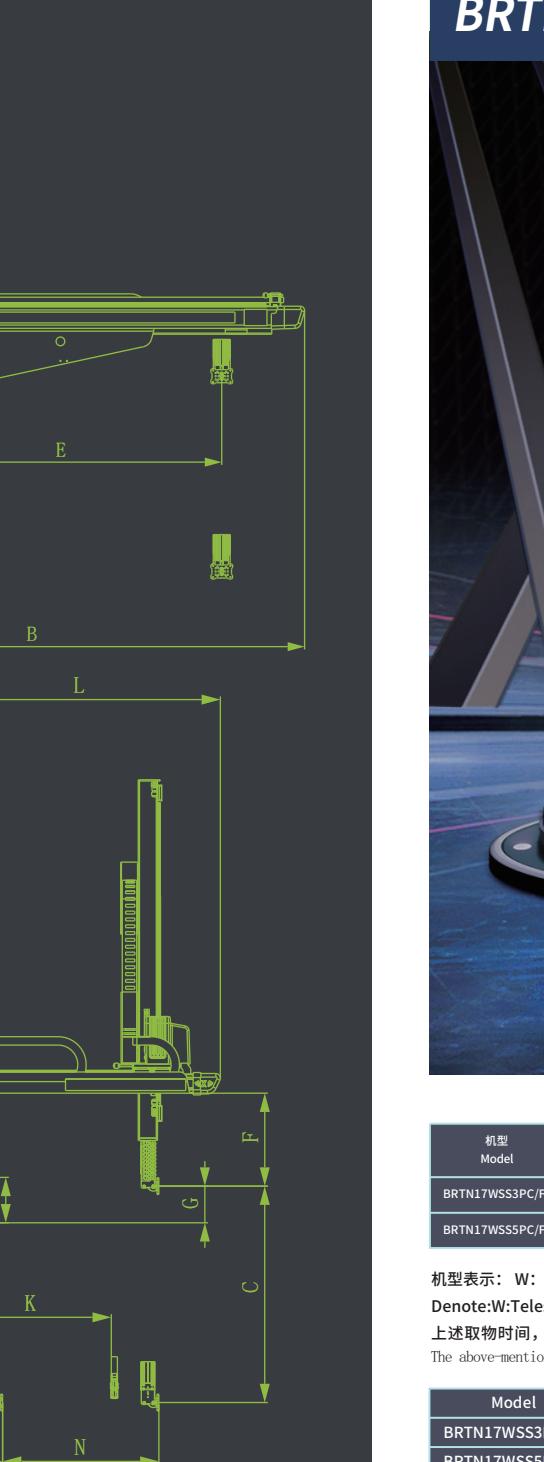
上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

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Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N
BRTM09IDS5PC/FC	1856	2275	900	394	1500	386.5	152.5	189	92	500	650	1195	290	650
BRTM11IDS5PC/FC	2025	2470	1100	393	1700	402	133	178	92	500	770	1315	295	770

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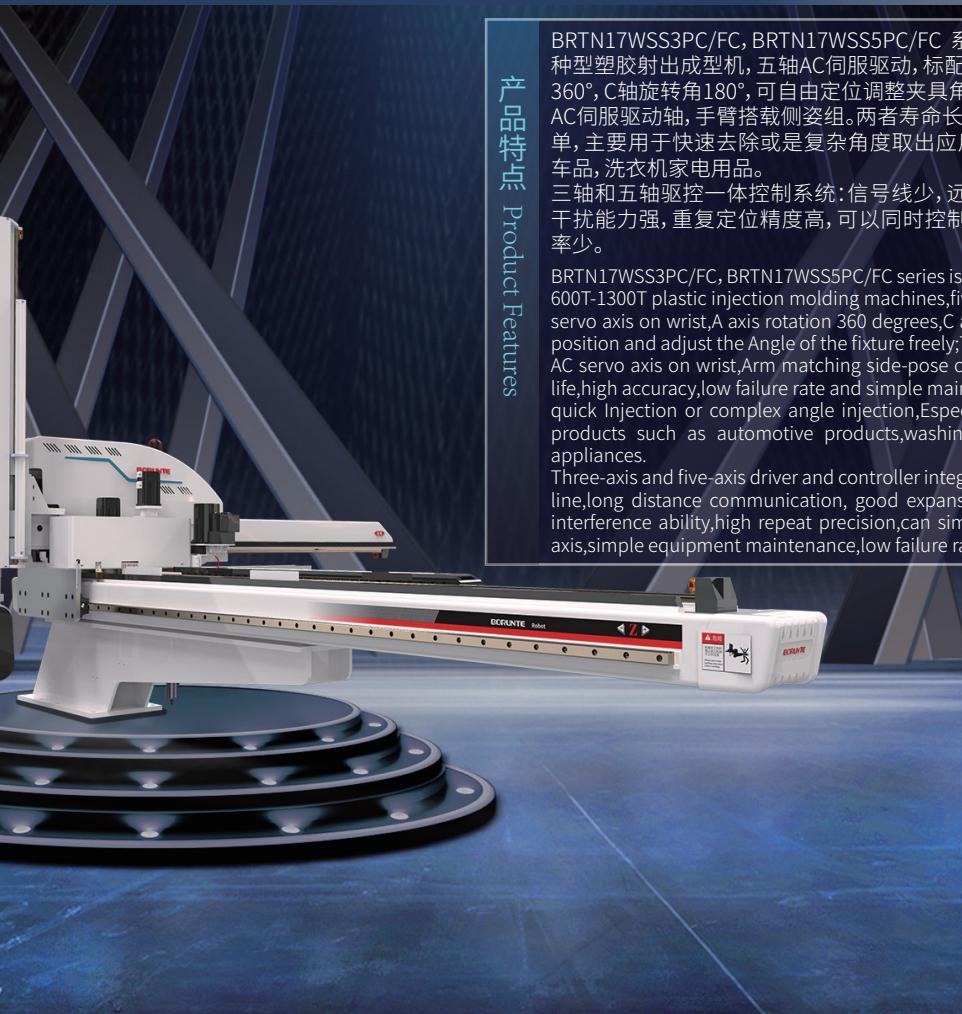


BRTN Series

三/五轴伺服机械手
Three/Five-axis servo Robot

BRTN17WSS3PC/FC
¥ 90000

BRTN17WSS5PC/FC
¥ 90000



机型 Model	电源容量 (KVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTN17WSS3PC/FC	3.3	600T-1300T	AC伺服马达 AC Servo motor	四吸两拖 Four-suction two-pull	2500	1430	1700	20	5.21	15.54	15	775
BRTN17WSS5PC/FC	4.2	600T-1300T	AC伺服马达 AC Servo motor	四吸两拖 Four-suction two-pull	2500	1430	1700	20	5.21	15.54	15	790

机型表示：W: 双截式 S:单臂机械手（成品臂） S5: 五轴AC伺服马达驱动（成品臂上下、AC轴、引拔+横行）

Denote:W:Telescopic type. S:Product arm. S5:Five-axis driven by AC Servo Motor(Traverse-axis, AC-axis, Vertical-axis+Crosswise-axis).

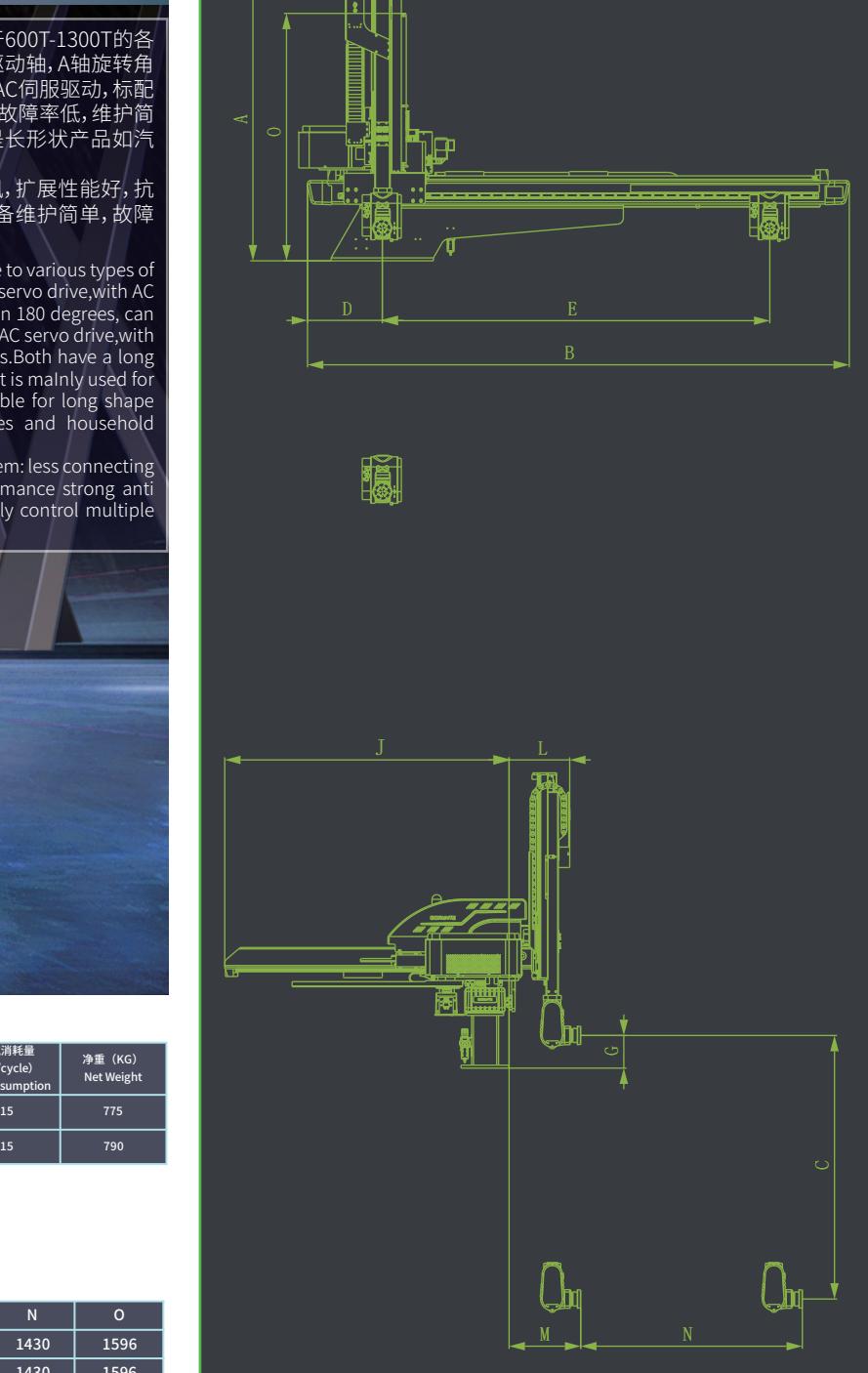
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Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
BRTN17WSS3PC/FC	1904.5	3495	1700	485	2500	/	190.5	/	/	1835	/	391	327	1430	1596
BRTN17WSS5PC/FC	1904.5	3495	1700	483	2500	/	211	/	/	1835	/	391	462	1430	1596

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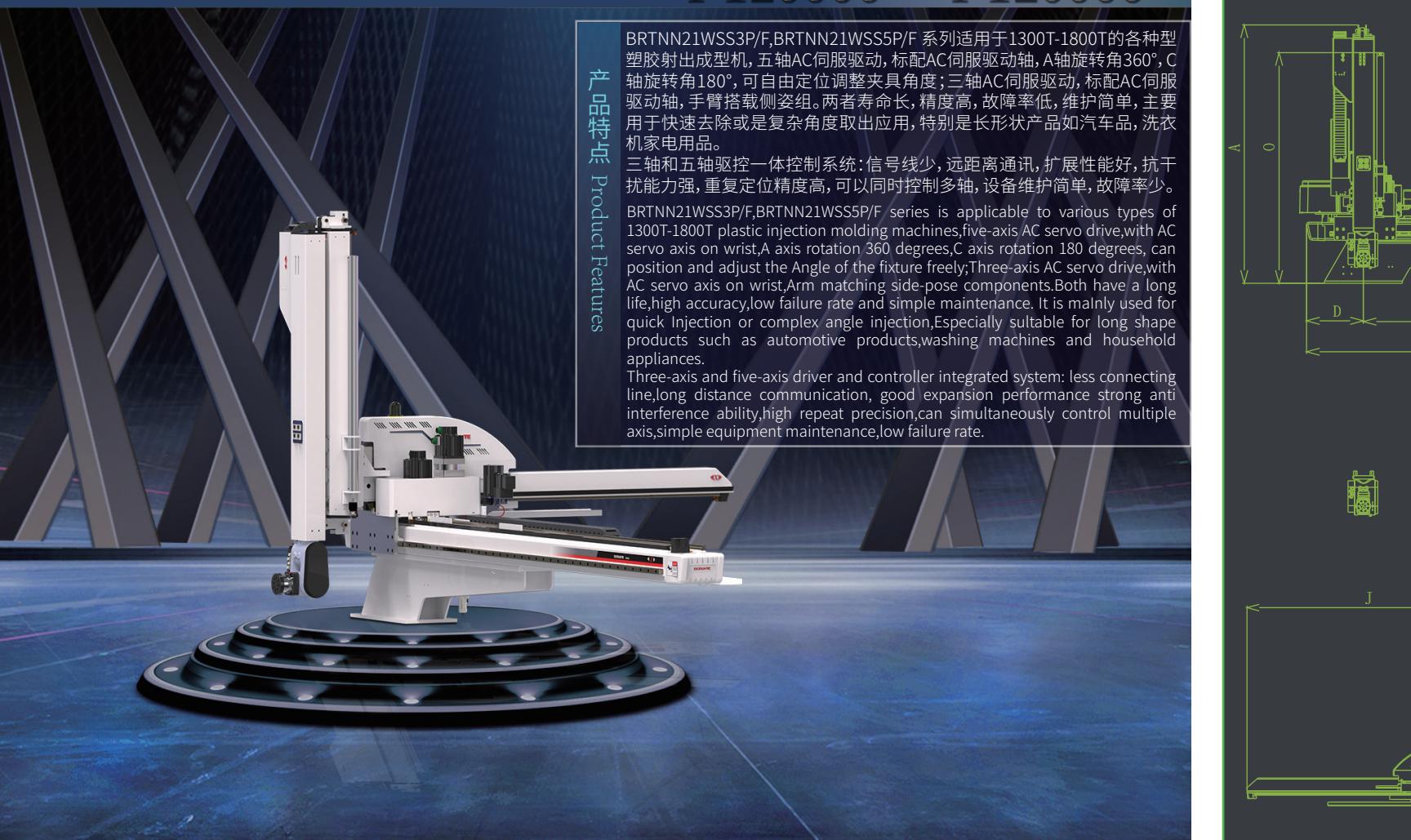


BRTN Series

三/五轴伺服机械手
Three/Five-axis servo Robot

BRTNN21WSS3P/F
¥ 120000

BRTNN21WSS5P/F
¥ 120000



机型 Model	电源容量 (kVA) Power Source	适用成型机 (ton) Recommended M.M	驱动方式 Traverse Driven	治具型式 Model of EOAT	横行行程 (mm) Traverse Stroke	引拔行程 (mm) Crosswise Stroke	上下行程 (mm) Vertical Stroke	最大荷载 (kg) Max. Loading	取出时间 (sec) Dry Take Out Time	全循环时间 (sec) Dry Cycle Time	空气消耗量 (NL/cycle) Air Consumption	净重 (KG) Net Weight
BRTNN21WSS3P/F	3.5	1300-1800T	AC伺服马达 AC Servo motor	四吸两拖	2800	1710	2100	30	4.62	16.5	15	860
BRTNN21WSS5P/F	4.8	1300-1800T	AC伺服马达 AC Servo motor	四吸两拖	2800	1710	2100	30	4.62	16.5	15	870

机型表示: W: 双截式 S:单臂机械手 (成品臂) S5: 五轴AC伺服马达驱动 (成品臂上下、AC轴、引拔+横行)

Denote:W:Telescopic type. S:Product arm S5:Five-axis driven by AC Servo Motor(Traverse-axis、AC-axis、Vertical-axis+Crosswise-axis).

上述取物时间，循环时间为我司内部测试标准测试结果，在机器实际应用过程中会因实际使用行程，负载，调试参数不同而有所变化。

The above-mentioned cycle time are the results of our internal test standard. In the actual application process of the machine, they will vary according to the actual operation

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
BRTNN21WSS3P/F	2191	3805	2100	484	2800	/	197	/	/	2136	/	474	477.5	1710	1956
BRTNN21WSS5P/F	2191	3805	2100	481	2800	/	210	/	/	2136	/	474	604.5	1710	1956

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